# On generalized $\Phi$-strongly monotone mappings and algorithms for the solution of equations of Hammerstein type 

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#### Abstract

In this paper, we consider the class of generalized $\Phi$-strongly monotone mappings and the methods of approximating a solution of equations of Hammerstein type. Auxiliary mapping is defined for nonlinear integral equations of Hammerstein type. The auxiliary mapping is the composition of bounded generalized $\Phi$-strongly monotone mappings which satisfy the range condition. Suitable conditions are imposed to obtain the boundedness and to show that the auxiliary mapping is a generalized $\Phi$-strongly which satisfies the range condition. A sequence is constructed and it is shown that it converges strongly to a solution of equations of Hammerstein type. The results in this paper improve and extend some recent corresponding results on the approximation of a solution of equations of Hammerstein type.


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## 1. Introduction

Let $E$ be a real normed linear space and $E^{*}$ denotes its corresponding dual space. We denote the value of the functional $x^{*} \in E^{*}$ at $x \in E$ by $\left\langle x^{*}, x\right\rangle$, domain of $A$ by $D(A)$, range of $A$ by $R(A)$ and $N(A)$ denotes the set of zeros of $A$ (i.e., $\left.N(A)=\{x \in D(A): 0 \in A x\}=A^{-1} 0\right)$. A multivalued

[^0]mapping $A: E \rightarrow 2^{E^{*}}$ from $E$ into $2^{E^{*}}$ is said to be monotone if for each $x, y \in E$, the following inequality holds:
$$
\langle\mu-\nu, x-y\rangle \geq 0 \quad \forall \mu \in A x, \quad \nu \in A y .
$$

A single-valued mapping $A: D(A) \subset E \rightarrow E^{*}$ is monotone if $\langle A x-A y, x-y\rangle \geq 0, \forall x, y \in D(A)$. For a linear mapping $A$, the above definition reduces to $\langle A u, u\rangle \geq 0 \forall u \in D(A)$. Multivalued mapping $A$ is said to be generalized $\Phi$-strongly monotone if there exists a strictly increasing function $\Phi:[0, \infty) \rightarrow[0, \infty)$ with $\Phi(0)=0$ such that for each $x, y \in D(A)$,

$$
\langle\mu-\nu, x-y\rangle \geq \Phi(\|x-y\|) \forall \mu \in A x, \quad \nu \in A y .
$$

Given that $H$ is a real Hilbert space, a mapping $A: H \rightarrow 2^{H}$ is said to be monotone if for each $x, y \in H$,

$$
\langle\mu-\nu, x-y\rangle \geq 0 \quad \forall \mu \in A x, \quad \nu \in A y .
$$

Let $A$ be a monotone mapping defined on $H$. It is well known (see e.g., Zeidler [32]) that many physically significant problems can be modelled by initial-value problems of the form

$$
\begin{equation*}
u^{\prime}(t)+A u(t)=0, u(0)=u_{0} . \tag{1.1}
\end{equation*}
$$

Heat, wave and Schrödinger equations are typical examples where such evolution equations occur. At an equilibrium state (that is, if $u(t)$ is independent of $t$ ), then (1.1) reduces to

$$
\begin{equation*}
A u=0 \tag{1.2}
\end{equation*}
$$

Therefore, considerable research efforts have been devoted, especially within the past 40 years or so, to methods of finding approximate solutions (when they exist) of (1.2). One important generalization of (1.2) is the so-called equation of Hammerstein type (see, e.g., Hammerstein [18]), where a nonlinear integral equation of Hammerstein type is one of the form

$$
\begin{equation*}
u(x)+\int_{\Omega} k(x, y) f(y, u(y)) d y=h(x) \tag{1.3}
\end{equation*}
$$

where $d y$ stands for a $\sigma$-finite measure on the measure space $\Omega$, the kernel $k$ is defined on $\Omega \times \Omega$, $f$ is a real-valued function defined on $\Omega \times \mathbb{R}$ and is in general nonlinear, $h$ is a given function on $\Omega$ and $u$ is the unknown function defined on $\Omega$. Let $g$ be a function from $\Omega \times \mathbb{R}^{n}$ into $\mathbb{R}$. We denote by $\mathcal{F}(X, Y)$, the set of all maps from $X$ to $Y$. The Nemystkii operator associated to $g$ is the operator $N_{g}: \mathcal{F}\left(\Omega, \mathbb{R}^{n}\right) \rightarrow \mathcal{F}(\Omega, \mathbb{R})$ defined by

$$
u \mapsto N_{g}(u)
$$

where $\left(N_{g} u\right)(x)=g(x, u(x)) \forall u \in \mathcal{F}\left(\Omega, \mathbb{R}^{n}\right), \forall x \in \Omega$. For simplicity, we shall write $N_{g} u(x)$ instead of $\left(N_{g} u\right)(x)$.

Example 1.1. Given a map $g: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
g(x, s)=|s| \forall(x, s) \in \mathbb{R} \times \mathbb{R}
$$

the Nemystkii operator associated to $g$ is the expression $N_{g} u(x)=|u(x)|$ for any map $u: \mathbb{R} \rightarrow \mathbb{R}$ and for any $x \in \mathbb{R}$.

Example 1.2. Given a map $g: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ defined by

$$
g(x, s)=x e^{s} \forall(x, s) \in \mathbb{R} \times \mathbb{R}
$$

the Nemystkii operator associated to $g$ is the expression $N_{g} u(x)=x e^{u(x)}$ for any map $u: \mathbb{R} \rightarrow \mathbb{R}$ and for any $x \in \mathbb{R}$.

Observe that by the continuity of $g, N_{g}$ maps the set of real-valued continuous function on $\Omega$; $C(\Omega)$ into itself. Moreover, it maps the set of real-valued measurable function into itself. Define the operator $K: \mathcal{F}(\Omega, \mathbb{R}) \rightarrow \mathcal{F}(\Omega, \mathbb{R})$ by

$$
K v(x)=\int_{\Omega} k(x, y) v(y) d y \text { for almost all } x \in \Omega
$$

and the Nemystkii operator $F: \mathcal{F}(\Omega, \mathbb{R}) \rightarrow \mathcal{F}(\Omega, \mathbb{R})$ associated with $f$ by

$$
F u(x)=f(x, u(x)) \text { for almost all } x \in \Omega,
$$

then the integral (1.3) can be put in functional equation form as follows:

$$
\begin{equation*}
u+K F u=0 \tag{1.4}
\end{equation*}
$$

where without loss of generality, we have taken $h \equiv 0$. Also, Hammerstein equations play crucial roles in solving several problems that arise in differential equations (see, e.g., Pascali and Sburlan [24], Chapter IV, p. 164) and applicable in theory of optimal control systems and in automation and network theory (see, e.g., Dolezale [17]). Several authors have proved existence and uniqueness theorems for equations of the Hammerstein type (see, e.g., Brézis and F. E. Browder ([6, 7, 8]); Browder and Gupta [9]; Chepanovich [10]; De Figueiredo and Gupta [15]).

Let $C$ be a nonempty closed convex subset of a real Banach space $E$. A self-mapping $T: C \rightarrow C$ is said to be nonexpansive if $\|T x-T y\| \leq\|x-y\| \forall x, y \in C$. If $E$ is smooth, $T: C \rightarrow E$ is said to be firmly nonexpansive type (see e.g., [22]), if

$$
\langle T x-T y, J T x-J T y\rangle \leq\langle T x-T y, J x-J y\rangle \text { for all } x, y \in C,
$$

where $J: E \rightarrow 2^{E^{*}}$ is the normalized duality mapping defined in Section 2.
For the iterative approximation of solutions of (1.2), the monotonicity of $A$ is crucial. A mapping $A: E \rightarrow 2^{E^{*}}$ is said to be maximal monotone if it is monotone and $R(J+t A)$ is all of $E^{*}$ for some $t>0$. Given that $A$ is monotone and $R(J+t A)=E^{*}$ for all $t>0$, then $A$ is said to satisfy the range condition. Let $E$ be a uniformly smooth and uniformly convex Banach space and $A$, a maximal monotone or (a monotone mapping which satisfies the range condition). Then, one can define for all $t>0$, the resolvent $J_{t}: C \rightarrow D(A)$ by

$$
J_{t} x=\{z \in E: J x \in J z+t A z\}
$$

for all $x \in C$, where $C$ is a closed convex subset of $E$. The fact that $F\left(J_{t}\right)=A^{-1} 0$ is well known where $F\left(J_{t}\right)$ is the set of fixed points of $J_{t}$ (see e.g., [23, 25, 26]). There exists some interesting reports on the class of monotone mappings (See e.g, 11, 3, 13, 16, 30]).

In this present work, it is shown that if $A$ is a multivalued generalized $\Phi$-strongly monotone mapping and such that $R\left(J_{p}+t_{0} A\right)=E^{*}$ for some $t_{0}>0$, then $R\left(J_{p}+t A\right)=E^{*}$ for all $t>0$, where $J_{p}, p>1$ is the generalized duality mapping. That is, a maximal monotone mapping satisfies the range condition. Also, a strong convergence theorem for approximating a solution of equations of Hammerstein type is established. We consider the generalized $\Phi$-strongly monotone mapping which is the largest such that if a solution of the equation $0 \in A x$ exists, it is necessarily unique. Our results generalize and improve some important and recent results of Chidume and Idu [12].

## 2. Preliminaries

Let $S:=\{x \in E:\|x\|=1\}$ denotes a unit sphere of a Banach space $E$ with dimension greater than or equal to two. The space $E$ is said to be G $\hat{a}$ teaux differentiable (or is smooth) if the limit

$$
\lim _{t \rightarrow 0} \frac{\|x+t y\|-\|x\|}{t}
$$

exists for each $x, y \in S$. If $E$ is smooth and the limit is attained uniformly for each $x, y \in S$, then it is said to be uniformly smooth. A Banach space $E$ is said to be strictly convex if

$$
\|x\|=\|y\|=1, x \neq y \Rightarrow \frac{\|x+y\|}{2}<1
$$

The space $E$ is said to be uniformly convex if, for each $\epsilon \in(0,2]$, there exists a $\delta:=\delta(\epsilon)>0$ such that for each $x, y \in S,\|x-y\| \geq \delta$ implies that $\frac{\|x-y\|}{2} \leq 1-\delta . E$ is reflexive if and only if the natural embedding of $E$ into $E^{* *}$ is onto. It is known that a uniformly convex Banach space is reflexive and strictly convex. Also, if $E$ is a reflexive Banach space, then, it is strictly convex (respectively smooth) if and only if $E^{*}$ is smooth (respectively strictly convex).

Let $\varphi:[0, \infty) \rightarrow[0, \infty)$ be a strictly increasing continuous function such that $\varphi(0)=0$ and $\varphi(t) \rightarrow \infty$ as $t \rightarrow \infty, \varphi$ is called a gauge function. We associate to $\varphi$, the duality mapping $J_{\varphi}: E \rightarrow 2^{E^{*}}$ which is defined as

$$
J_{\varphi}(x)=\left\{f \in E^{*}:\langle x, f\rangle=\|x\|\|f\|,\|f\|=\varphi(\|x\|)\right\}
$$

where $E^{*}$ denotes the dual space of $E$ and $\langle.,$.$\rangle denotes the generalized duality pairing. If \varphi(t)=$ $t^{p-1}, p>1$, the duality mapping $J_{\varphi}=J_{p}$ is called generalized duality mapping. The duality mapping with guage $\varphi(t)=t$ (i.e. $p=2$ ) is denoted by $J$ and is referred to as the normalized duality mapping. It follows from the definition that $J_{\varphi}(x)=\frac{\varphi(\|x\|)}{\|x\|} J(x)$ for each $x \neq 0$ and $J_{p}(x)=\|x\|^{p-2} J(x), p>1$. $J_{\varphi}$ is single-valued if $E$ is smooth and if $E$ is a reflexive strictly convex Banach space with strictly convex dual space $E^{*}, J_{p}: E \rightarrow E^{*}$ and $J_{q}: E^{*} \rightarrow E$ being the duality mappings with gauge functions $\varphi(t)=t^{p-1}$ and $\varphi(s)=s^{q-1}, \frac{1}{p}+\frac{1}{q}=1$, respectively, then $J_{p}^{-1}=J_{q}$. For a Banach space $E$ and $E^{*}$ as its dual space, the following properties of the generalized duality mapping have also been established (see e.g., Alber and Ryazantseva [5], Cioranescu [14], p. 25-77, Xu and Roach [29], Zălinescu [31):
(i) If $E$ is smooth, then $J_{p}$ is single-valued and norm-to-weak* continuous;
(ii) If $E$ is strictly convex, then $J_{p}$ is strictly monotone (injective, in particular, i.e, if $x \neq y$, then $\left.J_{p} x \cap J_{p} y=\emptyset\right)$;
(iii) If $E$ is reflexive, then $J_{p}$ is onto;
(iv) The expression $\left\langle J_{p} x, x\right\rangle$ is naturally regarded as having power $p$ as $\left\langle J_{p} x, x\right\rangle=\|x\|^{p}$;
(v) If $E$ is uniformly smooth, then $J_{q}: E^{*} \rightarrow E$ is a generalized duality mapping on $E^{*}, J_{p}^{-1}=$ $J_{q}, J_{p} J_{q}=I_{E^{*}}$ and $J_{q} J_{p}=I_{E}$, where $I_{E}$ and $I_{E^{*}}$ are the identity mappings on $E$ and $E^{*}$ respectively.

Definition 2.1. Let $E$ be a smooth real Banach space with dual space $E^{*}$, the followings were introduced by Aibinu and Mewomo [2].
(i) The function $\phi_{p}: E \times E \rightarrow \mathbb{R}$ is defined by

$$
\phi_{p}(x, y)=\frac{p}{q}\|x\|^{q}-p\left\langle x, J_{p} y\right\rangle+\|y\|^{p}, \text { for all } x, y \in E
$$

where $J_{p}$ is the generalized duality map from $E$ to $E^{*}, p$ and $q$ are real numbers such that $q \geq p>1$ and $\frac{1}{p}+\frac{1}{q}=1$. Notice that taking $p=2$ in 2.1), it reduces to

$$
\phi(x, y)=\|x\|^{2}-2\langle x, J y\rangle+\|y\|^{2}, \text { for all } x, y \in E
$$

which was introduced by Alber [4].
(ii) The mapping $V_{p}: E \times E^{*} \rightarrow \mathbb{R}$ is defined by

$$
V_{p}\left(x, x^{*}\right)=\frac{p}{q}\|x\|^{q}-p\left\langle x, x^{*}\right\rangle+\left\|x^{*}\right\|^{p} \quad \forall x \in E, x^{*} \in E^{*} \text { such that } q \geq p>1, \quad \frac{1}{p}+\frac{1}{q}=1 .
$$

Remark 2.2. These remarks follow from Definition 2.1:
(i) It is obvious from the definition of the function $\phi_{p}$ that

$$
\begin{equation*}
(\|x\|-\|y\|)^{p} \leq \phi_{p}(x, y) \leq(\|x\|+\|y\|)^{p} \text { for all } x, y \in E . \tag{2.1}
\end{equation*}
$$

(ii) Clearly, we also have that

$$
\begin{equation*}
V_{p}\left(x, x^{*}\right)=\phi_{p}\left(x, J^{-1} x^{*}\right) \quad \forall x \in E, \quad x^{*} \in E^{*} . \tag{2.2}
\end{equation*}
$$

In the sequel, we shall need the following lemmas.
Lemma 2.3. Aibinu and Mewomo [2]. Let E be a smooth uniformly convex real Banach space with $E^{*}$ as its dual. Then

$$
\begin{equation*}
V_{p}\left(x, x^{*}\right)+p\left\langle J^{-1} x^{*}-x, y^{*}\right\rangle \leq V_{p}\left(x, x^{*}+y^{*}\right) \tag{2.3}
\end{equation*}
$$

for all $x \in E$ and $x^{*}, y^{*} \in E^{*}$.
Lemma 2.4. Aibinu and Mewomo [2]. Let E be a smooth uniformly convex real Banach space. For $d>0$, let $B_{d}(0):=\{x \in E:\|x\| \leq d\}$. Then for arbitrary $x, y \in B_{d}(0)$,

$$
\|x-y\|^{p} \geq \phi_{p}(x, y)-\frac{p}{q}\|x\|^{q}, \quad q \geq p>1, \quad \frac{1}{p}+\frac{1}{q}=1 .
$$

Lemma 2.5. Aibinu and Mewomo [2]. Let E be a reflexive strictly convex and smooth real Banach space with the dual $E^{*}$. Then

$$
\begin{equation*}
\phi_{p}(y, x)-\phi_{p}(y, z) \geq p\langle z-y, J x-J z\rangle \text { for all } x, y, z \in E . \tag{2.4}
\end{equation*}
$$

Lemma 2.6. $X u$ [28]. Let $\left\{a_{n}\right\}$ be a sequence of nonnegative real numbers satisfying the following relations:

$$
a_{n+1} \leq\left(1-\alpha_{n}\right) a_{n}+\alpha_{n} \sigma_{n}+\gamma_{n}, \quad n \in \mathbb{N},
$$

where
(i) $\{\alpha\}_{n} \subset(0,1), \sum_{n=1}^{\infty} \alpha_{n}=\infty$;
(ii) $\lim \sup \{\sigma\}_{n} \leq 0$;
(iii) $\gamma_{n} \geq 0, \sum_{n=1}^{\infty} \gamma_{n}<\infty$.

Then, $a_{n} \rightarrow 0$ as $n \rightarrow \infty$.
Lemma 2.7. Chidume and Idu [12]. For a real number $p>1$, let $X, Y$ be real uniformly convex and uniformly smooth Banach spaces. Let $W:=X \times Y$ with the norm $\|w\|_{W}=\left(\|u\|_{X}^{p}+\|v\|_{Y}^{p}\right)^{\frac{1}{p}}$ for arbitrary $w:=(u, v) \in W$. Let $W^{*}:=X^{*} \times Y^{*}$ denotes the dual space of $Z$. For arbitrary $z=(u, v) \in Z$, define the map $j_{p}^{Z}: Z \rightarrow Z^{*}$ by

$$
j_{p}^{W}(z)=j_{p}^{W}(u, v)=\left(j_{p}^{X}(u), j_{p}^{Y}(v)\right)
$$

such that for arbitrary $w_{1}=\left(u_{1}, v_{1}\right), w_{2}=\left(u_{2}, v_{2}\right)$ in $Z$, the duality pairing $\langle.,$.$\rangle is given by$

$$
\left\langle w_{1}, j_{p}^{W}\left(w_{2}\right)\right\rangle=\left\langle u_{1}, j_{p}^{X}\left(u_{2}\right)\right\rangle+\left\langle v_{1}, j_{p}^{Y}\left(v_{2}\right)\right\rangle .
$$

Then,
(i) $W$ is uniformly smooth and uniformly convex,
(ii) $j_{p}^{W}$ is single-valued duality mapping on $W$.

Lemma 2.8. Chidume and Idu [12]. Let $E$ be a uniformly convex and uniformly smooth real Banach space. Let $F: E \rightarrow E^{*}$ and $K: E^{*} \rightarrow E$ be monotone mappings with $D(F)=R(K)=E$. Let $T: E \times E^{*} \rightarrow E^{*} \times E$ be defined by $T(u, v)=\left(J u-F u+v, J^{-1} v-K v-u\right)$ for all $(u, v) \in E \times E^{*}$, then $T$ is J-pseudocontractive. Moreover, if the Hammerstein equation $u+K F u=0$ has a solution in $E$, then $u^{*}$ is a solution of $u+K F u=0$ if and only if $\left(u^{*}, v^{*}\right) \in F_{E}^{J}(T)$, where $v^{*}=F u^{*}$.

Lemma 2.9. Zălinescu [31]. Let $\psi: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$be increasing with $\lim _{t \rightarrow \infty} \psi(t)=\infty$. Then $J_{\psi}^{-1}$ is single-valued and uniformly continuous on bounded sets of $E^{*}$ if and only if $E$ is a uniformly convex Banach space.

Theorem 2.10. $X u$ [27]. Let $E$ be a real uniformly convex Banach space. For arbitrary $r>0$, let $B_{r}(0):=\{x \in E:\|x\| \leq r\}$. Then, there exists a continuous strictly increasing convex function

$$
g:[0, \infty) \rightarrow[0, \infty), \quad g(0)=0
$$

such that for every $x, y \in B_{r}(0), j_{p}(x) \in J_{p}(x), j_{p}(y) \in J_{p}(y)$, the following inequalities hold:
(i) $\|x+y\|^{p} \geq\|x\|^{p}+p\left\langle y, j_{p}(x)\right\rangle+g(\|y\|)$;
(ii) $\left\langle x-y, j_{p}(x)-j_{p}(y)\right\rangle \geq g(\|x-y\|)$.

Lemma 2.11. B. T. Kien [21]. The dual space $E^{*}$ of a Banach space $E$ is uniformly convex if and only if the duality mapping $J_{p}$ is a single-valued map which is uniformly continuous on each bounded subset of $E$.

Lemma 2.12. Kamimura and Takahashi [19]. Let $E$ be a smooth uniformly convex real Banach space and let $\left\{x_{n}\right\}$ and $\left\{y_{n}\right\}$ be two sequences from $E$. If either $\left\{x_{n}\right\}$ or $\left\{y_{n}\right\}$ is bounded and $\phi\left(x_{n}, y_{n}\right) \rightarrow 0$ as $n \rightarrow \infty$, then $\left\|x_{n}-y_{n}\right\| \rightarrow 0$ as $n \rightarrow \infty$.
Theorem 2.13. Kido [20]. Let $E^{*}$ be a real strictly convex dual Banach space with a Fréchet differentiable norm and $A$ a maximal monotone operator from $E$ into $E^{*}$ such that $A^{-1} 0 \neq \emptyset$. Let $J_{t} x:=(J+t A)^{-1} x$ be the resolvent of $A$ and $P$ be the nearest point retraction of $E$ onto $A^{-1} 0$. Then, for every $x \in E$, $J_{t} x$ converges strongly to $P x$ as $t \rightarrow \infty$.

## 3. Main Results

We give and prove the following lemmas which are useful in establishing our main result.
Lemma 3.1. Suppose $E$ is a Banach space with the dual $E^{*}$. Let $F: E \rightarrow E^{*}$ and $K: E^{*} \rightarrow E$ be mappings such that $D(K)=R(F)$ and the following conditions hold:
(i) For each $u_{1}, u_{2} \in E$, there exists a strictly increasing function $\Phi_{1}:[0, \infty) \rightarrow[0, \infty)$ with $\Phi_{1}(0)=0$ such that

$$
\left\langle F u_{1}-F u_{2}, u_{1}-u_{2}\right\rangle \geq \Phi_{1}\left(\left\|u_{1}-u_{2}\right\|\right) ;
$$

(ii) For each $v_{1}, v_{2} \in E^{*}$, there exists a strictly increasing function $\Phi_{2}:[0, \infty) \rightarrow[0, \infty)$ with $\Phi_{2}(0)=0$ such that

$$
\left\langle K u_{1}-K u_{2}, v_{1}-v_{2}\right\rangle \geq \Phi_{2}\left(\left\|v_{1}-v_{2}\right\|\right) ;
$$

(iii) $\Phi_{i}(t) \geq r_{i} t$ for $t \in[0, \infty)$ and $r_{i}>0, i=1,2$.

Let $W:=E \times E^{*}$ with norm $\|w\|_{W}:=\|u\|_{E}+\|v\|_{E^{*}}$ for $w=(u, v) \in W$. Define a mapping $A: W \rightarrow W^{*}$ by $A w:=(F u-v, u+K v)$.
(i) Then for each $w_{1}, w_{2} \in W$, there exists a strictly increasing function $\Phi:[0, \infty) \rightarrow[0, \infty)$ with $\Phi(0)=0$ such that

$$
\left\langle A w_{1}-A w_{2}, w_{1}-w_{2}\right\rangle \geq \Phi\left(\left\|w_{1}-w_{2}\right\|\right) ;
$$

(ii) Suppose that $F$ and $K$ are bounded mappings, then $A$ is a bounded map.

## Proof .

(i) Define $\Phi:[0, \infty) \rightarrow[0, \infty)$ by $\Phi(t):=\min \left\{r_{1}, r_{2}\right\} t$ for each $t \in[0, \infty)$. Clearly, $\Phi$ is a strictly increasing function with $\Phi(0)=0$. For $w_{1}=\left(u_{1}, v_{1}\right), \quad w_{2}=\left(u_{2}, v_{2}\right) \in W$, we have $A w_{1}=\left(F u_{1}-v_{1}, K v_{1}+u_{1}\right)$ and $A w_{2}=\left(F u_{2}-v_{2}, K v_{2}+u_{2}\right)$ such that

$$
A w_{1}-A w_{2}=\left(F u_{1}-F u_{2}-\left(v_{1}-v_{2}\right), K v_{1}-K v_{2}+\left(u_{1}-u_{2}\right)\right)
$$

Therefore, the following estimate follows from the properties of $F$ and $K$.

$$
\begin{aligned}
\left\langle A w_{1}-A w_{2}, w_{1}-w_{2}\right\rangle= & \left\langle F u_{1}-F u_{2}-\left(v_{1}-v_{2}\right), u_{1}-u_{2}\right\rangle \\
& +\left\langle K v_{1}-K v_{2}+\left(u_{1}-u_{2}\right), v_{1}-v_{2}\right\rangle \\
= & \left\langle F u_{1}-F u_{2}, u_{1}-u_{2}\right\rangle-\left\langle v_{1}-v_{2}, u_{1}-u_{2}\right\rangle \\
& +\left\langle K v_{1}-K v_{2}, v_{1}-v_{2}\right\rangle+\left\langle u_{1}-u_{2}, v_{1}-v_{2}\right\rangle \\
\geq & \Phi_{1}\left(\left\|u_{1}-u_{2}\right\|\right)+\Phi_{2}\left(\left\|v_{1}-v_{2}\right\|\right) \\
\geq & r_{1}\left\|u_{1}-u_{2}\right\|+r_{2}\left\|v_{1}-v_{2}\right\| \\
\geq & \min \left\{r_{1}, r_{2}\right\}\left(\left\|u_{1}-u_{2}\right\|+\left\|v_{1}-v_{2}\right\|\right) \\
= & \Phi\left(\left\|w_{1}-w_{2}\right\|\right) .
\end{aligned}
$$

(ii) By the definition of $A$, it is a bounded map since $F$ and $K$ are bounded mappings.

Remark 3.2. Recall that a mapping $A: E \rightarrow E^{*}$ is said to be strongly monotone if there exists a constant $k \in(0,1)$ such that

$$
\langle A x-A y, x-y\rangle \geq k\|x-y\|^{2} \quad \forall \quad x, y \in D(A) .
$$

Therefore for a strongly monotone mapping, it is required that the norm on $W$ be defined as

$$
\|w\|_{W}^{2}:=\|u\|_{E}^{2}+\|v\|_{E^{*}}^{2}
$$

An analogue of Lemma 2.5, Chidume and Djitte, [11, which was proved in a Hilbert space is given below in a uniformly smooth and uniformly convex Banach space.

Lemma 3.3. Let $E$ be a uniformly smooth and uniformly convex Banach space with dual $E^{*}$. Suppose $D(A)=E$ and $A: E \rightarrow 2^{E^{*}}$ is a multivalued generalized $\Phi$-strongly monotone mapping such that $R\left(J_{p}+t_{0} A\right)=E^{*}$ for some $t_{0}>0$. Then $A$ satisfies the range condition, that is, $R\left(J_{p}+t A\right)=E^{*}$ for all $t>0$.

Proof . By the strict convexity of $E$, we obtain for every $x \in E$, there exist unique $x_{t_{0}} \in E$ and such that

$$
J_{p} x \in J_{p} x_{t_{0}}+t_{0} A x_{t_{0}} .
$$

Taking $J_{p_{t_{0}}}(x)=x_{t_{0}}$, one can define a single-valued mapping $J_{p_{t_{0}}}: E \rightarrow D(F)$ by

$$
J_{p_{t_{0}}}:=\left(J_{p}+t_{0} A\right)^{-1} J_{p}
$$

$J_{p_{t_{0}}}$ is called the resolvent of $A$. It is known that $\left(J_{p}+t_{0} A\right)$ is a bijection since it is monotone and $R\left(J_{p}+t_{0} A\right)=E^{*}$. Since $E$ is a smooth and strictly convex Banach space and $A: E \rightarrow 2^{E^{*}}$ is such that $R\left(J_{p}+t_{0} A\right)=E^{*}$, for each $t_{0}>0$, one can verify that the resolvent $J_{p_{t_{0}}}$ of $A$, defined by

$$
J_{p_{t_{0}}}(x)=\left\{z \in E: J_{p} x \in J_{p} z+t_{0} A z\right\}=\left\{\left(J_{p}+t_{0} A\right)^{-1} J_{p} x\right\}
$$

for all $x \in E$ is a firmly nonexpansive type map. Infact, for $x_{1}, x_{2} \in E$ and $t_{0}>0$, and for every $J_{p_{t_{0}}}\left(x_{1}\right), J_{p_{t_{0}}}\left(x_{2}\right) \in D(F)$, we have that $\frac{J_{p} x_{1}-J_{p}\left(J_{p_{t_{0}}}\left(x_{1}\right)\right)}{t_{0}}, \frac{J_{p} x_{2}-J_{p}\left(J_{p_{0}}\left(x_{2}\right)\right)}{t_{0}} \in A$, and generalized $\Phi$-strongly monotonicity property of $A$ gives,

$$
\begin{aligned}
& \left\langle\frac{J_{p} x_{1}-J_{p}\left(J_{p_{t_{0}}}\left(x_{1}\right)\right)}{t_{0}}-\frac{J_{p} x_{2}-J_{p}\left(J_{p_{t_{0}}}\left(x_{2}\right)\right)}{t_{0}}, \quad J_{p_{t_{0}}}\left(x_{1}\right)-J_{p_{t_{0}}}\left(x_{2}\right)\right\rangle \geq \\
& \Phi\left(\left\|J_{p_{t_{0}}}\left(x_{1}\right)-J_{p_{t_{0}}}\left(x_{2}\right)\right\|\right) \geq 0 .
\end{aligned}
$$

Consequently,

$$
\begin{align*}
& \left\langle J_{p}\left(J_{p_{t_{0}}}\left(x_{1}\right)\right)-J_{p}\left(J_{p_{t_{0}}}\left(x_{2}\right)\right), \quad J_{p_{t_{0}}}\left(x_{1}\right)-J_{p_{t_{0}}}\left(x_{2}\right)\right\rangle \leq \\
& \left\langle J_{p} x_{1}-J_{p} x_{2}, \quad J_{p_{t_{0}}}\left(x_{1}\right)-J_{p_{t_{0}}}\left(x_{2}\right)\right\rangle . \tag{3.1}
\end{align*}
$$

Thus, the resolvent $J_{p_{t_{0}}}$ is a firmly nonexpansive type map. A simple computation from (3.1) shows that for $x, y \in E$,

$$
\begin{equation*}
\left\|J_{p_{t_{0}}}(x)-J_{p_{t_{0}}}(y) \mid \leq\right\| x-y \| . \tag{3.2}
\end{equation*}
$$

We claim that

$$
R\left(J_{p}+t A\right)=E^{*}
$$

for any $t>\frac{t_{0}}{2}$. Indeed, let $t>\frac{t_{0}}{2}$, for every $x \in E$, we solve the equation

$$
\begin{equation*}
J_{p} x+t A x=w^{*}, x^{*} \in E^{*} \tag{3.3}
\end{equation*}
$$

Notice that $x \in E$ is a solution of (3.3) provided that

$$
J_{p} x+t_{0} A x=\frac{t_{0}}{t} w^{*}+\left(1-\frac{t_{0}}{t}\right) J_{p} x
$$

which is equivalent to

$$
x=J_{p_{t_{0}}}\left(\frac{t_{0}}{t} w^{*}+\left(1-\frac{t_{0}}{t}\right) J_{p} x\right) .
$$

By the contraction mapping principle, Eq. (3.3) has a unique solution since $\left|1-\frac{t_{0}}{t}\right|<1$ and this justifies the claim. It is given that $A$ is a monotone mapping and $R\left(J_{p}+t_{0} A\right)=E^{*}$ for some $t_{0}>0$. By the claim, it follows that $R\left(J_{p}+t A\right)=E^{*}$ for any $t>\frac{t_{0}}{2}$. By induction, we therefore have that $R\left(J_{p}+t A\right)=E^{*}$ for any $t>\frac{t_{0}}{2^{n}}$ and any $n \in \mathbb{N}$. Thus, $R\left(J_{p}+t A\right)=E^{*}$ for any $t>0$.

Lemma 3.4. Let $E$ be a uniformly smooth and uniformly convex real Banach space and denote the dual space by $E^{*}$. Suppose $F: E \rightarrow E^{*}$ is a generalized $\Phi_{1}$-strongly monotone mapping such that $R\left(J_{p}+t_{1} F\right)=E^{*}$ for all $t_{1}>0$ and $K: E^{*} \rightarrow E$ is a generalized $\Phi_{2}$-strongly monotone mapping such that $R\left(J_{q}+t_{2} K\right)=E$ for all $t_{2}>0$. Let $W:=E \times E^{*}$ with norm $\|w\|_{W}:=\|u\|_{E}+\|v\|_{E^{*}} \forall w=$ $(u, v) \in W$ and define a map $A: W \rightarrow W^{*}$ by

$$
\begin{equation*}
A w=(F u-v, K v+u), \forall w=(u, v) \in W \tag{3.4}
\end{equation*}
$$

then $R\left(J_{p}+t A\right)=W^{*}$ for all $t>0$.
Proof . We show that $R\left(J_{p}+t A\right)=W^{*}$ for all $t>0$. Indeed, let $t_{0}$ be such that $0<t_{0}<1$. Denote the resolvents $J_{p_{t_{0}}}: E \rightarrow D(F)$ of $F$ by $J_{p_{t_{0}}}:=\left(J_{p}+t_{0} F\right)^{-1} J_{p}$ and $J_{q_{t_{0}}}: E^{*} \rightarrow D(K)$ of $K$ by $J_{q_{t_{0}}}=\left(J_{q}+t_{0} K\right)^{-1} J_{q} . J_{p_{t_{0}}}$ and $J_{q_{t_{0}}}$ are firmly nonexpansive type maps and hence 3.2 holds. Therefore, for $h:=\left(h_{1}, h_{2}\right) \in X^{*}$, define $G: W \rightarrow W$ by

$$
G w=\left(J_{p_{t_{0}}}\left(h_{2}-t_{0} u\right), \quad J_{q_{t_{0}}}\left(h_{1}+t_{0} v\right)\right), \forall w=(u, v) \in W .
$$

From the fact that 3.2 holds for $J_{p_{t_{0}}}$ and $J_{t_{t_{0}}}$, we have

$$
\left\|G w_{1}-G w_{2}\right\| \leq t_{0}\left\|w_{1}-w_{2}\right\| \quad \forall \quad w_{1}, w_{2} \in W
$$

Therefore $G$ is a contraction and by Banach contraction mapping principle, $G$ has a unique fixed point $w^{*}:=\left(u^{*}, v^{*}\right) \in W$, that is $G w^{*}=w^{*}$ or equivalently $u^{*}=J_{p_{t_{0}}}\left(h_{2}-t_{0} u^{*}\right), v^{*}=J_{q_{t_{0}}}\left(h_{1}+t_{0} v^{*}\right)$. These imply that $\left(J_{p}+t_{0} A\right) w=h$. Lemma 3.1 gives that $A$ is a generalized $\Phi$-strongly monotone mapping and by Lemma 3.3, $R\left(J_{p}+t A\right)=W^{*}$ for all $t>0$.

Theorem 3.5. Let $E$ be a uniformly smooth and uniformly convex real Banach space and denote the dual space by $E^{*}$. Let $F: E \rightarrow E^{*}$ be a generalized $\Phi_{1}$-strongly monotone mapping such that $R\left(J_{p}+t_{1} F\right)=E^{*}$ for all $t_{1}>0$ and $K: E^{*} \rightarrow E$ be a generalized $\Phi_{2}$-strongly monotone mapping such that $R\left(J_{q}+t_{2} K\right)=E$ for all $t_{2}>0$. Suppose $F$ and $K$ are bounded mappings such that $D(K)=R(F)=E^{*}$. Define $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ iteratively for arbitrary $u_{1} \in E$ and $v_{1} \in E^{*}$ by

$$
\begin{align*}
& u_{n+1}=J_{q}\left(J_{p} u_{n}-\lambda_{n}\left(F u_{n}-v_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)\right), n \in \mathbb{N},  \tag{3.5}\\
& v_{n+1}=J_{p}\left(J_{q} v_{n}-\lambda_{n}\left(K v_{n}+u_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right)\right), n \in \mathbb{N}, \tag{3.6}
\end{align*}
$$

where $J_{p}$ is the generalized duality mapping from $E$ to $E^{*}$ and $J_{q}$ is the generalized duality mapping from $E^{*}$ to $E$. Let the real sequences $\left\{\lambda_{n}\right\}$ and $\left\{\theta_{n}\right\}$ in $(0,1)$ be such that,
(i) $\lim \theta_{n}=0$ and $\left\{\theta_{n}\right\}$ is decreasing;
(ii) $\sum_{n=1}^{\infty} \lambda_{n} \theta_{n}=\infty$;
(iii) $\lim _{n \rightarrow \infty}\left(\left(\theta_{n-1} / \theta_{n}\right)-1\right) / \lambda_{n} \theta_{n}=0, \quad \sum_{n=1}^{\infty} \lambda_{n}<\infty$.

Suppose that $u+K F u=0$ has a solution in E. There exists a real constant $\gamma_{0}>0$ with $\psi\left(\lambda_{n} M\right) \leq$ $\gamma_{0}, \quad n \in \mathbb{N}$ for some constant $M>0$. Then, the sequence $\left\{u_{n}\right\}$ converges strongly to the solution of $0=u+K F u$.

Proof . Let $W:=E \times E^{*}$ with norm $\|x\|_{W}^{p}:=\|u\|_{E}^{p}+\|v\|_{E^{*}}^{p} \forall w=(u, v) \in W$ and define $\wedge_{p}: W \times W \rightarrow \mathbb{R}$ by

$$
\wedge_{p}\left(w_{1}, w_{2}\right)=\phi_{p}\left(u_{1}, u_{2}\right)+\phi_{p}\left(v_{1}, v_{2}\right),
$$

where respectively $w_{1}=\left(u_{1}, v_{1}\right)$ and $w_{2}=\left(u_{2}, v_{2}\right)$. Let $u^{*} \in E$ be a solution of $u+K F u=0$. Observe that setting $v^{*}:=F u^{*}$ and $w^{*}:=\left(u^{*}, v^{*}\right)$, we have that $u^{*}=-K v^{*}$.

We divide the proof into two parts.
Part 1: We prove that $\left\{w_{n}\right\}$ is bounded, where $w_{n}:=\left(u_{n}, v_{n}\right)$. Let $r>0$ be sufficiently large such that

$$
\begin{equation*}
\Phi\left(\frac{\delta}{2}\right) \geq r \geq \max \left\{4 \wedge_{p}\left(w^{*}, w_{1}\right), \delta^{p}+\frac{p}{q}\left\|x^{*}\right\|^{q}\right\} \tag{3.7}
\end{equation*}
$$

where $\delta$ is a positive real number and $\Phi:=\min \left\{\Phi_{1}, \Phi_{2}\right\}$. The proof is by induction. By construction, $\wedge_{p}\left(w^{*}, w_{1}\right) \leq r$. Suppose that $\wedge_{p}\left(w^{*}, w_{n}\right) \leq r$ for some $n \in \mathbb{N}$. We show that $\wedge_{p}\left(w^{*}, w_{n+1}\right) \leq r$. Suppose this is not the case, then $\wedge_{p}\left(w^{*}, w_{n+1}\right)>r$.
From inequality 2.1), we have $\left\|w_{n}\right\| \leq r^{\frac{1}{p}}+\left\|w^{*}\right\|$. Let $B:=\left\{w \in E: \wedge_{p}\left(w^{*}, w\right) \leq r\right\}$ and notice that by Lemma 2.9 and 2.11, $J_{q}$ and $J_{p}$ are uniformly continuous on bounded subsets. Consequently, since $F$ and $K$ are bounded, we define

$$
\begin{align*}
& M_{1}:=\sup \left\{\left\|F u+\theta_{n}\left(J_{p} u-J_{p} u_{1}\right)\right\|: \theta_{n} \in(0,1), u \in B\right\}+1,  \tag{3.8}\\
& M_{2}:=\sup \left\{\left\|K v+\theta_{n}\left(J_{p} v-J_{p} v_{1}\right)\right\|: \theta_{n} \in(0,1), v \in B\right\}+1 . \tag{3.9}
\end{align*}
$$

Let $\psi_{1}:[0, \infty) \rightarrow[0, \infty)$ be the modulus of continuity of $J_{q}$ and $\psi_{2}:[0, \infty) \rightarrow[0, \infty)$ be the modulus of continuity of $J_{p}$. Recall that by the uniform continuity of $J_{q}$ and $J_{p}$ on bounded subsets of $E^{*}$ and $E$ respectively. Then we have

$$
\begin{equation*}
\left\|J_{q}\left(J_{p} u_{n}\right)-J_{q}\left(J_{p} u_{n}-\lambda_{n}\left(F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)\right)\right\| \leq \psi_{1}\left(\lambda_{n} M_{1}\right) \tag{3.10}
\end{equation*}
$$

$$
\begin{equation*}
\left\|J_{p}\left(J_{q} v_{n}\right)-J_{p}\left(J_{q} v_{n}-\lambda_{n}\left(K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right)\right)\right\| \leq \psi_{2}\left(\lambda_{n} M_{2}\right) \tag{3.11}
\end{equation*}
$$

Let $M_{0}:=M_{1}+M_{2}$, since $\Phi:=\min \left\{\Phi_{1}, \Phi_{2}\right\}$, one can define

$$
\gamma_{0}:=\min \left\{1, \frac{\Phi\left(\frac{\delta}{2}\right)}{2 M_{0}}\right\} \text { where } \psi\left(\lambda_{n} M_{0}\right) \leq \gamma_{0} \text { with } \psi\left(\lambda_{n} M_{0}\right) \geq \frac{\delta}{2},
$$

and $\psi:=\psi_{1}+\psi_{2}$. Applying Lemma 2.3 with $y^{*}:=\lambda_{n}\left(F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)$ and by using the definition of $u_{n+1}$, we compute as follows,

$$
\begin{aligned}
\phi_{p}\left(u^{*}, u_{n+1}\right)= & \phi_{p}\left(u^{*}, J_{q}\left(J_{p} u_{n}-\lambda_{n}\left(F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)\right)\right) \\
= & V_{p}\left(u^{*}, J_{p} u_{n}-\lambda_{n}\left(F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)\right) \\
\leq & V_{p}\left(u^{*}, J_{p} u_{n}\right) \\
& -p \lambda_{n}\left\langle J_{q}\left(J_{p} u_{n}-\lambda_{n}\left(F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)\right)-u^{*}, F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right\rangle \\
= & \phi_{p}\left(u^{*}, u_{n}\right)-p \lambda_{n}\left\langle u_{n}-u^{*}, F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right\rangle \\
& -p \lambda_{n}\left\langle J_{q}\left(J_{p} u_{n}-\lambda_{n}\left(F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)\right)-u_{n}, F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right\rangle .
\end{aligned}
$$

By Schwartz inequality and uniform continuity property of $J_{q}$ on bounded sets of $E^{*}$ (Lemma 2.9), we obtain

$$
\begin{aligned}
\phi_{p}\left(u^{*}, u_{n+1}\right) \leq & \phi_{p}\left(u^{*}, u_{n}\right)-p \lambda_{n}\left\langle u_{n}-u^{*}, F u_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right\rangle \\
& \left.+p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1} \text { (By applying inequality (3.10)}\right) \\
\leq & \left.\phi_{p}\left(u^{*}, u_{n}\right)-p \lambda_{n}\left\langle u_{n}-u^{*}, F x_{n}-F u^{*}\right\rangle \text { since } u^{*} \in N(F)\right) \\
& -p \lambda_{n} \theta_{n}\left\langle u_{n}-u^{*}, J_{p} u_{n}-J_{p} u_{1}\right\rangle+p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1} .
\end{aligned}
$$

By Lemma 2.5, $p\left\langle u_{n}-u^{*}, J_{p} u_{1}-J_{p} u_{n}\right\rangle \leq \phi_{p}\left(u^{*}, u_{1}\right)-\phi_{p}\left(u^{*}, u_{n}\right) \leq \phi_{p}\left(u^{*}, u_{1}\right)$. Also, since $F$ is generalized $\Phi$-strongly monotone, we have,

$$
\begin{align*}
\phi_{p}\left(u^{*}, u_{n+1}\right) \leq & \phi_{p}\left(u^{*}, u_{n}\right)-p \lambda_{n} \Phi_{1}\left(\left\|u_{n}-u^{*}\right\|\right) \\
& +p \lambda_{n} \theta_{n}\left\langle u_{n}-u^{*}, J_{p} u_{1}-J_{p} u_{n}\right\rangle+p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1} \\
\leq & \phi_{p}\left(u^{*}, u_{n}\right)-p \lambda_{n} \Phi_{1}\left(\left\|u_{n}-u^{*}\right\|\right)+p \lambda_{n} \theta_{n} \phi_{p}\left(u^{*}, u_{1}\right)+p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1} . \tag{3.12}
\end{align*}
$$

By the uniform continuity property of $J_{q}$ on bounded sets of $E^{*}$, we have

$$
\left\|u_{n+1}-u_{n}\right\|=\left\|J_{q}\left(J_{p} u_{n+1}\right)-J_{q}\left(J_{p} u_{n}\right)\right\| \leq \psi_{1}\left(\lambda_{n} M_{1}\right)
$$

such that

$$
\left\|u_{n+1}-u^{*}\right\|-\left\|u_{n}-u^{*}\right\| \leq \psi_{1}\left(\lambda_{n} M_{1}\right)
$$

which gives

$$
\begin{equation*}
\left\|u_{n}-u^{*}\right\| \geq\left\|u_{n+1}-u^{*}\right\|-\psi_{1}\left(\lambda_{n} M_{1}\right) \tag{3.13}
\end{equation*}
$$

From Lemma 2.4,

$$
\begin{aligned}
\left\|u_{n+1}-u^{*}\right\|^{p} & \geq \phi_{p}\left(u^{*}, u_{n+1}\right)-\frac{p}{q}\left\|u^{*}\right\| \\
& \geq r-\frac{p}{q}\left\|u^{*}\right\| \\
& \geq\left(\delta^{p}+\frac{p}{q}\left\|u^{*}\right\|\right)-\frac{p}{q}\left\|u^{*}\right\| \\
& \geq \delta^{p} .
\end{aligned}
$$

So,

$$
\left\|u_{n+1}-u^{*}\right\| \geq \delta
$$

Therefore, the inequality (3.13) becomes,

$$
\begin{aligned}
\left\|u_{n}-u^{*}\right\| & \geq \delta-\psi_{1}\left(\lambda_{n} M_{1}\right) \\
& \geq \frac{\delta}{2} .
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\Phi_{1}\left(\left\|u_{n}-u^{*}\right\|\right) \geq \Phi_{1}\left(\frac{\delta}{2}\right) \tag{3.14}
\end{equation*}
$$

Substituting (3.14) into (3.12) gives

$$
\begin{align*}
\phi_{p}\left(u^{*}, u_{n+1}\right) \leq & \phi_{p}\left(u^{*}, u_{n}\right)-p \lambda_{n} \Phi_{1}\left(\frac{\delta}{2}\right)+p \lambda_{n} \theta_{n} \phi_{p}\left(u^{*}, u_{1}\right) \\
& +p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1} . \tag{3.15}
\end{align*}
$$

Similarly,

$$
\begin{aligned}
\phi_{q}\left(v^{*}, v_{n+1}\right)= & \phi_{p}\left(v^{*}, J_{q}\left(J_{p} v_{n}-\lambda_{n}\left(K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right)\right)\right) \\
= & V_{p}\left(v^{*}, J_{q} v_{n}-\lambda_{n}\left(K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right)\right) \\
\leq & V_{p}\left(v^{*}, J_{q} v_{n}\right) \\
& -p \lambda_{n}\left\langle J_{p}\left(J_{q} v_{n}-\lambda_{n}\left(K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right)\right)-v^{*}, K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right\rangle \\
= & \phi_{p}\left(v^{*}, v_{n}\right)-p \lambda_{n}\left\langle v_{n}-v^{*}, K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right\rangle \\
& -p \lambda_{n}\left\langle J_{p}\left(J_{q} v_{n}-\lambda_{n}\left(K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right)\right)-v_{n}, K v_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right\rangle .
\end{aligned}
$$

By Schwartz inequality and uniform continuity property of $J$ on bounded subsets of $E$ (Lemma 2.11), we obtain

$$
\begin{aligned}
\phi_{p}\left(v^{*}, v_{n+1}\right) \leq & \phi_{p}\left(v^{*}, v_{n}\right)-p \lambda_{n}\left\langle v_{n}-v^{*}, F x_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right\rangle \\
& +p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1}(\text { By applying inequality (3.11) }) \\
\leq & \left.\phi_{p}\left(u^{*}, u_{n}\right)-p \lambda_{n}\left\langle u_{n}-u^{*}, K v_{n}-K v^{*}\right\rangle \text { since } v^{*} \in N(K)\right) \\
& -p \lambda_{n} \theta_{n}\left\langle v_{n}-v^{*}, J_{q} v_{n}-J_{q} v_{1}\right\rangle+p \lambda_{n} \psi_{2}\left(\lambda_{n} M_{2}\right) M_{2} .
\end{aligned}
$$

By Lemma 2.5, $p\left\langle v_{n}-v^{*}, J_{q} v_{1}-J_{q} v_{n}\right\rangle \leq \phi_{p}\left(v^{*}, v_{1}\right)-\phi_{p}\left(v^{*}, v_{n}\right) \leq \phi_{p}\left(v^{*}, v_{1}\right)$. Also, since $K$ is generalized $\Phi$-strongly monotone, we have,

$$
\begin{align*}
\phi_{p}\left(v^{*}, v_{n+1}\right) \leq & \phi_{p}\left(v^{*}, v_{n}\right)-p \lambda_{n} \Phi_{2}\left(\left\|v_{n}-v^{*}\right\|\right) \\
& +p \lambda_{n} \theta_{n}\left\langle v_{n}-v^{*}, J_{q} v_{1}-J_{q} v_{n}\right\rangle+p \lambda_{n} \psi_{2}\left(\lambda_{n} M_{2}\right) M_{2} \\
\leq & \phi_{p}\left(v^{*}, v_{n}\right)-p \lambda_{n} \Phi_{2}\left(\left\|v_{n}-v^{*}\right\|\right)+p \lambda_{n} \theta_{n} \phi_{p}\left(v^{*}, v_{1}\right)+p \lambda_{n} \psi_{2}\left(\lambda_{n} M_{2}\right) M_{2} . \tag{3.16}
\end{align*}
$$

By the uniform continuity property of $J_{p}$ on bounded sets of $E^{*}$, we have

$$
\left\|v_{n+1}-v_{n}\right\|=\left\|J_{p}\left(J_{q} v_{n+1}\right)-J_{p}\left(J_{q} v_{n}\right)\right\| \leq \psi_{2}\left(\lambda_{n} M_{2}\right)
$$

such that

$$
\left\|v_{n+1}-v^{*}\right\|-\left\|v_{n}-v^{*}\right\| \leq \psi_{2}\left(\lambda_{n} M_{2}\right),
$$

which gives

$$
\begin{equation*}
\left\|v_{n}-v^{*}\right\| \geq\left\|v_{n+1}-v^{*}\right\|-\psi_{2}\left(\lambda_{n} M_{2}\right) . \tag{3.17}
\end{equation*}
$$

From Lemma 2.4 ,

$$
\begin{aligned}
\left\|v_{n+1}-v^{*}\right\|^{p} & \geq \phi_{p}\left(v^{*}, v_{n+1}\right)-\frac{p}{q}\left\|v^{*}\right\| \\
& \geq r-\frac{p}{q}\left\|u^{*}\right\| \\
& \geq\left(\delta^{p}+\frac{p}{q}\left\|v^{*}\right\|\right)-\frac{p}{q}\left\|v^{*}\right\| \\
& \geq \delta^{p} .
\end{aligned}
$$

So,

$$
\left\|v_{n+1}-v^{*}\right\| \geq \delta
$$

Therefore, the inequality (3.17) becomes,

$$
\begin{aligned}
\left\|v_{n}-v^{*}\right\| & \geq \delta-\psi_{2}\left(\lambda_{n} M_{2}\right) \\
& \geq \frac{\delta}{2} .
\end{aligned}
$$

Thus,

$$
\begin{equation*}
\Phi_{2}\left(\left\|v_{n}-v^{*}\right\|\right) \geq \Phi_{2}\left(\frac{\delta}{2}\right) . \tag{3.18}
\end{equation*}
$$

Substituting (3.18) into (3.16) gives

$$
\begin{align*}
\phi_{p}\left(v^{*}, v_{n+1}\right) \leq & \phi_{p}\left(v^{*}, v_{n}\right)-p \lambda_{n} \Phi_{2}\left(\frac{\delta}{2}\right)+p \lambda_{n} \theta_{n} \phi_{p}\left(v^{*}, v_{1}\right) \\
& +p \lambda_{n} \psi_{2}\left(\lambda_{n} M_{2}\right) M_{2} . \tag{3.19}
\end{align*}
$$

Add (3.15) and (3.19) gives

$$
\begin{aligned}
r<\wedge_{p}\left(w^{*}, w_{n+1}\right) & \leq \wedge_{p}\left(w^{*}, w_{n}\right)-p \lambda_{n} \Phi\left(\frac{\delta}{2}\right)+p \lambda_{n} \theta_{n} \wedge_{p}\left(w^{*}, w_{1}\right)+p \lambda_{n} \psi\left(\lambda_{n} M_{0}\right) M_{0} \\
& \leq \wedge_{p}\left(w^{*}, w_{n}\right)-p \lambda_{n} \Phi\left(\frac{\delta}{2}\right)+p \lambda_{n} \theta_{n} \wedge_{p}\left(w^{*}, w_{1}\right)+p \lambda_{n} \gamma_{0} M_{0} \\
& \leq \wedge_{p}\left(w^{*}, w_{n}\right)-\frac{p \lambda_{n}}{2} \Phi\left(\frac{\delta}{2}\right)+p \lambda_{n} \theta_{n} \wedge_{p}\left(w^{*}, w_{1}\right) \\
& \leq \wedge_{p}\left(w^{*}, w_{n}\right)-\frac{p \lambda_{n}}{2} \Phi\left(\frac{\delta}{2}\right)+p \lambda_{n} \theta_{n} \wedge_{p}\left(w^{*}, w_{1}\right) \\
& \left.\leq \wedge_{p}\left(w^{*}, w_{n}\right)-\frac{p \lambda_{n}}{2} \Phi\left(\frac{\delta}{2}\right)+p \lambda_{n} \wedge_{p}\left(w^{*}, w_{1}\right) \quad \text { Since } \theta_{n} \in(0,1)\right) \\
& \leq r-\frac{p r \lambda_{n}}{2}+\frac{p r \lambda_{n}}{4} \\
& =r-\frac{p r \lambda_{n}}{4}<r,
\end{aligned}
$$

a contradiction. Hence, $\wedge_{p}\left(w^{*}, w_{n+1}\right) \leq r$. By induction, $\wedge_{p}\left(w^{*}, w_{n}\right) \leq r \quad \forall \quad n \in \mathbb{N}$. Thus, from inequality (2.1), $\left\{w_{n}\right\}$ is bounded.

Part 2: Define $A: W \rightarrow W^{*}$ by $A w=(F u-v, K v+u), \quad \forall w=(u, v) \in W$. We show that $\left\{w_{n}\right\}$ strongly converges to a solution of $A w=0$. Since $A$ satisfies the range condition (Lemma 3.3) and by the strict convexity of $X$ (Lemma 2.7), we obtain for every $t>0$, and $w \in W$, there exists a unique $w_{t} \in D(A)$, where $D(A)$ is the domain of $A$ such that

$$
J_{p}^{W} w \in J_{p}^{W} w_{t}+t A w_{t}
$$

Taking $J_{t} w=w_{t}$, then we define a single-valued mapping $J_{t}: E \rightarrow D(A)$ by $J_{t}=\left(J_{p}^{W}+t A\right)^{-1} J_{p}^{W}$. Such a $J_{t}$ is called the resolvent of $A$. Therefore, by Theorem 2.13, for each $n \in \mathbb{N}$, there exists a unique $x_{n} \in D(A)$ such that,

$$
x_{n}=\left(J_{p}^{W}+\frac{1}{\theta_{n}} A\right)^{-1} J_{p}^{W} w_{1} .
$$

Then, setting $x_{n}:=\left(y_{n}, z_{n}\right) \in E \times E^{*}$ and $w_{1}:=\left(u_{1}, v_{1}\right) \in E \times E^{*}$, we have

$$
\left(y_{n}, z_{n}\right)=\left(J_{p}^{W}+\frac{1}{\theta_{n}} A\right)^{-1} J_{p}^{W}\left(u_{1}, v_{1}\right)
$$

which is equivalent to

$$
\left(J_{p}^{W}+\frac{1}{\theta_{n}} A\right)\left(y_{n}, z_{n}\right)=J_{p}^{W}\left(u_{1}, v_{1}\right) .
$$

Since $A\left(y_{n}, z_{n}\right)=\left(F y_{n}-z_{n}, K z_{n}+y_{n}\right)$, then,

$$
\begin{aligned}
J_{p} y_{n}+\frac{1}{\theta_{n}}\left(F y_{n}-z_{n}\right) & =J_{p} u_{1} \\
J_{q} z_{n}+\frac{1}{\theta_{n}}\left(K z_{n}+y_{n}\right) & =J_{q} v_{1}
\end{aligned}
$$

and these lead to

$$
\begin{align*}
& \theta_{n}\left(J_{p} y_{n}-J_{p} u_{1}\right)+F y_{n}-z_{n}=0,  \tag{3.20}\\
& \theta_{n}\left(J_{q} z_{n}-J_{q} v_{1}\right)+K z_{n}+y_{n}=0 . \tag{3.21}
\end{align*}
$$

Notice that the sequences $\left\{y_{n}\right\}$ and $\left\{z_{n}\right\}$ are bounded because they are convergent sequences by Theorem 2.13. Moreover, by Theorem 2.13, $\lim x_{n} \in A^{-1} 0$. Let $y_{n} \rightarrow u^{*}$ and $z_{n} \rightarrow v^{*}$, then $u^{*}$ in $E$ solves the equation $u+K F u=0$ if and only if $x^{*}=\left(u^{*}, v^{*}\right)$ is a solution of $A x=0$ in $W$ for $v^{*}=F u^{*} \in E^{*}$. The implication is that

$$
\begin{aligned}
& F u^{*}-v^{*}=0 \\
& K v^{*}+u^{*}=0
\end{aligned}
$$

Following the same arguments as in part 1, we get,

$$
\begin{equation*}
\phi_{p}\left(y_{n}, u_{n+1}\right) \leq \phi_{p}\left(y_{n}, u_{n}\right)-p \lambda_{n}\left\langle u_{n}-y_{n}, F u_{n}-v_{n}+\theta_{n}\left(J u_{n}-J u_{1}\right)\right\rangle+p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1} \tag{3.22}
\end{equation*}
$$

and

$$
\begin{equation*}
\phi_{p}\left(z_{n}, v_{n+1}\right) \leq \phi_{p}\left(z_{n}, v_{n}\right)-p \lambda_{n}\left\langle v_{n}-z_{n}, K v_{n}+u_{n}+\theta_{n}\left(J_{q} v_{n}-J_{q} v_{1}\right)\right\rangle+p \lambda_{n} \psi_{2}\left(\lambda_{n} M_{2}\right) M_{2} \tag{3.23}
\end{equation*}
$$

By Theorem 2.10, Lemma 2.4 and Eq. 3.20), the generalized $\Phi$-strongly monotonicity of $F$ is used to obtain for some $p>1$,

$$
\begin{aligned}
& \left\langle u_{n}-y_{n}, F u_{n}-v_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right\rangle \\
= & \left\langle x_{n}-y_{n}, F u_{n}-v_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} y_{n}+J_{p} y_{n}-J_{p} u_{1}\right)\right\rangle \\
= & \theta_{n}\left\langle u_{n}-y_{n}, J_{p} u_{n}-J_{p} y_{n}\right\rangle+\left\langle u_{n}-y_{n}, F u_{n}-v_{n}+\theta_{n}\left(J_{p} y_{n}-J_{p} u_{1}\right)\right\rangle \\
= & \theta_{n}\left\langle u_{n}-y_{n}, J_{p} u_{n}-J_{p} y_{n}\right\rangle+\left\langle u_{n}-y_{n}, F u_{n}-v_{n}-\left(F y_{n}-z_{n}\right)\right\rangle \\
\geq & \theta_{n} g\left(\left\|u_{n}-y_{n}\right\|\right)+\Phi\left(\left\|u_{n}-y_{n}\right\|\right)+\left\langle u_{n}-y_{n}, z_{n}-v_{n}\right\rangle \\
\geq & \frac{1}{p} \theta_{n} \phi_{p}\left(y_{n}, u_{n}\right)+\left\langle u_{n}-y_{n}, z_{n}-v_{n}\right\rangle
\end{aligned}
$$

This makes the inequality (3.22) to become

$$
\begin{equation*}
\phi_{p}\left(y_{n}, u_{n+1}\right) \leq\left(1-\lambda_{n} \theta_{n}\right) \phi_{p}\left(y_{n}, u_{n}\right)-p \lambda_{n}\left\langle u_{n}-y_{n}, z_{n}-v_{n}\right\rangle+p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1} . \tag{3.24}
\end{equation*}
$$

From Lemma 2.5, we obtain that

$$
\begin{align*}
\phi_{p}\left(y_{n}, u_{n}\right) & \leq \phi_{p}\left(y_{n-1}, u_{n}\right)-p\left\langle y_{n}-u_{n}, J_{p} y_{n-1}-J_{p} y_{n}\right\rangle \\
& =\phi_{p}\left(y_{n-1}, u_{n}\right)+p\left\langle u_{n}-y_{n}, J_{p} y_{n-1}-J_{p} y_{n}\right\rangle \\
& \leq \phi_{p}\left(y_{n-1}, u_{n}\right)+\left\|J_{p} y_{n-1}-J_{p} y_{n}\right\|\left\|u_{n}-y_{n}\right\| . \tag{3.25}
\end{align*}
$$

Let $R>0$ such that $\left\|x_{1}\right\| \leq R,\left\|y_{n}\right\| \leq R$ for all $n \in \mathbb{N}$. Then the estimates below follows from (3.20),

$$
J_{p} y_{n-1}-J_{p} y_{n}+\frac{1}{\theta_{n}}\left(F y_{n-1}-z_{n-1}-\left(F y_{n}-z_{n}\right)=\frac{\theta_{n-1}-\theta_{n}}{\theta_{n}}\left(J_{p} u_{1}-J_{p} y_{n-1}\right) .\right.
$$

Taking the duality pairing of each side of this equation with respect to $y_{n-1}-y_{n}$ and using the generalized $\Phi$-strongly monotonicity property of $F$, then

$$
\left\langle J_{p} y_{n-1}-J_{p} y_{n}, y_{n-1}-y_{n}\right\rangle \leq \frac{\theta_{n-1}-\theta_{n}}{\theta_{n}}\left\|J_{p} u_{1}-J_{p} y_{n-1}\right\|\left\|y_{n-1}-y_{n}\right\|,
$$

which gives,

$$
\begin{equation*}
\left\|J_{p} y_{n-1}-J_{p} y_{n}\right\| \leq\left(\frac{\theta_{n-1}}{\theta_{n}}-1\right)\left\|J_{p} y_{n-1}-J_{p} u_{1}\right\| . \tag{3.26}
\end{equation*}
$$

Using (3.25) and (3.26), the inequality (3.22) becomes

$$
\begin{align*}
\phi_{p}\left(y_{n}, u_{n+1}\right) \leq & \left(1-\lambda_{n} \theta_{n}\right) \phi_{p}\left(y_{n-1}, u_{n}\right)+C_{1}\left(\frac{\theta_{n-1}}{\theta_{n}}-1\right) \\
& -p \lambda_{n}\left\langle u_{n}-y_{n}, z_{n}-v_{n}\right\rangle+p \lambda_{n} \psi_{1}\left(\lambda_{n} M_{1}\right) M_{1}, \tag{3.27}
\end{align*}
$$

for some constant $C_{1}>0$. Similar analysis gives that

$$
\begin{align*}
\phi_{p}\left(z_{n}, v_{n+1}\right) \leq & \left(1-\lambda_{n} \theta_{n}\right) \phi_{p}\left(z_{n-1}, v_{n}\right)+C_{2}\left(\frac{\theta_{n-1}}{\theta_{n}}-1\right) \\
& -p \lambda_{n}\left\langle v_{n}-z_{n}, u_{n}-y_{n}\right\rangle+p \lambda_{n} \psi_{2}\left(\lambda_{n} M_{2}\right) M_{2}, \tag{3.28}
\end{align*}
$$

for some constant $C_{2}>0$. Since $\psi:=\psi_{1}+\psi_{2}, M_{0}:=M_{1}+M_{2}$ and $\psi\left(\lambda_{n} M_{0}\right) \leq \gamma_{0}$, adding (3.26) and (3.28) generates

$$
\wedge\left(x_{n}, w_{n+1}\right) \leq\left(1-\lambda_{n} \theta_{n}\right) \wedge\left(x_{n-1}, w_{n}\right)+C\left(\frac{\theta_{n-1}}{\theta_{n}}-1\right)+p \lambda_{n} \gamma_{0} M_{0}
$$

where $C:=C_{1}+C_{2}>0$. By Lemma 2.6, $\phi\left(x_{n-1}, w_{n}\right) \rightarrow 0$ as $n \rightarrow \infty$ and using Lemma 2.12, we have that $w_{n}-x_{n-1} \rightarrow 0$ as $n \rightarrow \infty$. Since by Theorem 2.13, $x_{n} \rightarrow w^{*} \in N(A)$, we obtain that $w_{n} \rightarrow w^{*}$ as $n \rightarrow \infty$. But $w_{n}=\left(u_{n}, v_{n}\right)$ and $w^{*}=\left(u^{*}, v^{*}\right)$, this implies that $u_{n} \rightarrow u^{*}$ with $u^{*}$ the solution of the Hammerstein equation.

Corollary 3.6. Let $E$ be a uniformly smooth and uniformly convex real Banach space with the dual space $E^{*}$. Suppose $F: E \rightarrow E^{*}$ and $K: E^{*} \rightarrow E$ are bounded and strongly monotone mappings. Define $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ iteratively for arbitrary $u_{1} \in E$ and $v_{1} \in E^{*}$ by

$$
\begin{align*}
& u_{n+1}=J_{q}\left(J_{p} u_{n}-\lambda_{n}\left(F u_{n}-v_{n}+\theta_{n}\left(J_{p} u_{n}-J_{p} u_{1}\right)\right)\right), n \in \mathbb{N},  \tag{3.29}\\
& v_{n+1}=J_{p}\left(J_{q}^{*} v_{n}-\lambda_{n}\left(K v_{n}+u_{n}+\theta_{n}\left(J_{q}^{*} v_{n}-J_{q}^{*} v_{1}\right)\right)\right), n \in \mathbb{N}, \tag{3.30}
\end{align*}
$$

where $J_{p}: E \rightarrow E^{*}$ is the generalized duality mapping with the inverse, $J_{q}: E^{*} \rightarrow E$ and the real sequences $\left\{\lambda_{n}\right\}$ and $\left\{\theta_{n}\right\}$ in $(0,1)$ are such that,
(i) $\lim \theta_{n}=0$ and $\left\{\theta_{n}\right\}$ is decreasing;
(ii) $\sum_{n=1}^{\infty} \lambda_{n} \theta_{n}=\infty$;
(iii) $\lim _{n \rightarrow \infty}\left(\left(\theta_{n-1} / \theta_{n}\right)-1\right) / \lambda_{n} \theta_{n}=0, \quad \sum_{n=1}^{\infty} \lambda_{n}<\infty$.

Suppose that $u+K F u=0$ has a solution in E. There exists a real constant $\gamma_{0}>0$ with $\psi\left(\lambda_{n} M\right) \leq$ $\gamma_{0}, \quad n \in \mathbb{N}$ for some constant $M>0$. Then, the sequence $\left\{u_{n}\right\}$ converges strongly to the solution of $0=u+K F u$.

Proof . Define $\Phi_{1}\left(\left\|u_{1}-u_{2}\right\|\right):=k_{1}\left\|u_{1}-u_{2}\right\|^{2}$ and $\Phi_{2}\left(\left\|v_{1}-v_{2}\right\|\right):=k_{2}\left\|v_{1}-v_{2}\right\|^{2}$ for some constants $k_{1}, k_{2} \in(0,1)$ and let $W:=E \times E^{*}$ with norm $\|w\|_{W}^{2}:=\|u\|_{E}^{2}+\|v\|_{E^{*}}^{2} \forall w=(u, v) \in W$. The result follows from Theorem 3.5,

Corollary 3.7. Chidume and Idu [12]. Let $E$ be a uniformly convex and uniformly smooth real Banach space and $F: E \rightarrow E^{*}$, $K: E^{*} \rightarrow E$ be maximal monotone and bounded maps, respectively. For $\left(x_{1}, y_{1}\right),\left(u_{1}, v_{1}\right) \in E \times E^{*}$, define the sequences $\left\{u_{n}\right\}$ and $\left\{v_{n}\right\}$ in $E$ and $E^{*}$ respectively, by

$$
\begin{gather*}
u_{n+1}=J^{-1}\left(J u_{n}-\lambda_{n}\left(F u_{n}-v_{n}\right)-\lambda_{n} \theta_{n}\left(J u_{n}-J x_{1}\right)\right), \quad n \in \mathbb{N},  \tag{3.31}\\
v_{n+1}=J\left(J^{-1} v_{n}-\lambda_{n}\left(K v_{n}+u_{n}\right)-\lambda_{n} \theta_{n}\left(J^{-1} v_{n}-J^{-1} y_{1}\right)\right), \quad n \in \mathbb{N}, \tag{3.32}
\end{gather*}
$$

where $\left\{\lambda_{n}\right\}$ and $\left\{\theta_{n}\right\}$ are real sequences in $(0,1)$ satisfying the following conditions:
(i) $\sum_{n=1}^{\infty} \lambda_{n} \theta_{n}=\infty$,
(ii) $\lambda_{n} M_{0}^{*} \leq \gamma_{0} \theta_{n} ; \delta_{E}^{-1}\left(\lambda_{n} M_{0}^{*}\right) \leq \gamma_{0} \theta_{n}$,
(iii) $\frac{\delta_{E}^{-1}\left(\frac{\theta_{n-1-\theta_{n}}^{\theta_{n}}}{\theta_{n}} K\right)}{\lambda_{n}} \rightarrow 0 ; \frac{\delta_{E^{*}}^{-1}\left(\frac{\theta_{n-1}-\theta_{n}}{\theta_{n}} K\right)}{\lambda_{n} \theta_{n}} \rightarrow 0$ as $n \rightarrow \infty$,
(iv) $\frac{1}{2} \frac{\theta_{n-1}-\theta_{n}}{\theta_{n}} K \in(0,1)$,
for some constants $M_{0}^{*}>0$ and $\gamma_{0}>0$, where $\delta_{E}:(0, \infty) \rightarrow(0, \infty)$ is the modulus of convexity of $E$ and $K:=4 R L \sup \{\|J x-J y\|:\|x\| \leq R,\|y\| \leq R\}+1, \quad x, y \in E, \quad R>0$. Assume that the equation $u+K F u=0$ has a solution. Then the sequences $\left\{u_{n}\right\}_{n=1}^{\infty}$ and $\left\{v_{n}\right\}_{n=1}^{\infty}$ converge strongly to $u^{*}$ and $v^{*}$, respectively, where $u^{*}$ is the solution of $u+K F u=0$ with $v^{*}=F u^{*}$.

Proof . From Lemma 2.8, we see that $T: E \times E^{*} \rightarrow E^{*} \times E$ defined by $T(u, v)=(J u-F u+$ $\left.v, J^{-1} v-K v-u\right)$ for all $(u, v) \in E \times E^{*}$ is $J$-pseudocontractive and $A:=(J-T)$ is maximal monotone. Therefore, the iterative sequences (3.31) and (3.32) are respectively equivalent to

$$
\begin{align*}
u_{n+1} & =J^{-1}\left(J u_{n}-\lambda_{n}\left(F u_{n}+\theta_{n}\left(J u_{n}-J x_{1}\right)\right)\right), n \in \mathbb{N} \text { and }  \tag{3.33}\\
v_{n+1} & =J\left(J^{-1} v_{n}-\lambda_{n}\left(K v_{n}+\theta_{n}\left(J^{-1} v_{n}-J^{-1} y_{1}\right)\right)\right), n \in \mathbb{N} \tag{3.34}
\end{align*}
$$

where $J: E \rightarrow E^{*}$ is the normalized duality mapping with the inverse, $J^{-1}: E^{*} \rightarrow E$. Hence, the result follows from Theorem 3.5.

Remark 3.8. Prototype for our iteration parameters in Theorem 3.5 are, $\lambda_{n}=\frac{1}{(n+1)^{a}}$ and $\theta_{n}=$ $\frac{1}{(n+1)^{b}}$, where $0<b<a$ and $a<1$.

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