# Fixed point uniqueness of generalized $(\psi, \varphi)$-weak contractions in partially ordered metric spaces under suitable constraints 

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(Communicated by Asadollah Aghajani)


#### Abstract

In this paper, by providing an example, I show that the condition which produced by Radenović and Kadelburg in [Generalized weak contractions in partially ordered metric spaces, Comput. Math. Appl. 60 (2010) pp. 1776-1783] is not sufficient for uniqueness of the fixed point. Furthermore, a new sufficient condition is introduced for the uniqueness of the fixed point. Some suitable examples are furnished to demonstrate the validity of the hypotheses of my results.


Keywords: Fixed Point Uniqueness, Generalized $(\psi, \varphi)$-Weak Contraction, Ordered Metric Spaces
2010 MSC: Primary 47H10; Secondary 54H25

## 1 Introduction and Preliminaries

The study of fixed point theory in the setting of a partially ordered metric space was first started in 2004 by Ran and Reurings 11 and then by Nieto and López (see [6, 7). Many authors obtained several interesting results in ordered metric spaces, for example, see [3, 4, 5, 8, 10].

The following definitions and notations will be used in this paper.
Definition 1.1. 9 Let $(X, \preceq)$ be a partially ordered set and let $T$ and $S$ be two self-maps on $X$. Then

1) the elements $x, y \in X$ are comparable if $x \preceq y$ or $y \preceq x$ holds and we denote it by $x \preceq \succeq y$.
2) a subset $A$ of $X$ is said to be well ordered if any two elements of $A$ are comparable .
3) the ordered metric space $(X, \preceq, d)$ is called regular whenever if a nondecreasing sequence $\left\{x_{n}\right\}$ in $(X, \preceq)$ converges to $x \in X$, then $x_{n} \preceq x$, for all $n \in \mathbb{N}$.
4) $T$ is called nondecreasing with respect to $\preceq$ if $x \preceq y$ implies $T x \preceq T y$.
5) the mappings $T$ and $S$ are called weakly increasing if $T x \preceq S T x$ and $S x \preceq T S x$ for all $x \in X$. A mapping $T$ is called weakly increasing If $T$ and $T$ are weakly increasing maps which means that $T x \preceq T^{2} x$ for each $x \in X$.

The control functions were introduced by Đorić [1] as follows:

[^0]Definition 1.2. A pair $(\psi, \varphi)$ of self-maps on $[0, \infty)$ is called a pair of control functions, if the following conditions are satisfied:

1. $\psi$ is a continuous nondecreasing function and $\psi(t)=0$ if and only if $t=0$.
2. $\varphi$ is lower semi-continuous with $\varphi(t)=0$ if and only if $t=0$.

So far, many authors have studied fixed point theorems which are based on control functions (see, e.g. [1, 2, (9, 12]).
Consider the following notations:

- $m(x, y)=\max \left\{d(x, y), d(x, T x), d(y, S y), \frac{d(x, S y)+d(y, T x)}{2}\right\}$,
- $n(x, y)=\max \left\{d(x, y), \frac{d(x, T x)+d(y, S y)}{2}, \frac{d(x, S y)+d(y, T x)}{2}\right\}$,
- $m_{T}(x, y)=\max \left\{d(x, y), d(x, T x), d(y, T y), \frac{d(x, T y)+d(y, T x)}{2}\right\}$,
- $n_{T}(x, y)=\max \left\{d(x, y), \frac{d(x, T x)+d(y, T y)}{2}, \frac{d(x, T y)+d(y, T x)}{2}\right\}$,
for all $x, y \in X$, where $T$ and $S$ are two self-maps on the metric space $(X, d)$.

In 2010, Radenović and Kadelburg [9], studied generalized weak contractions in partially ordered metric spaces and extended result of Đorić [1, Harjani and Sadarangani [2], as well as Zhang and Song [12]. They obtained the following results:

Theorem 1.3. [9, Theorem 3.1] Let $(X, \preceq, d)$ be an ordered complete metric space and $(T, S)$ be a pair of weakly increasing maps on $X$ such that for any two comparable elements $x, y \in X$

$$
\begin{equation*}
\psi(d(T x, S y)) \leq \psi(m(x, y))-\phi(m(x, y)) \tag{1.1}
\end{equation*}
$$

where $(\psi, \varphi)$ is a pair of control functions.
Then $T$ and $S$ have a common fixed point, provided by at least one of the following cases holds:
(i) $T$ or $S$ is continuous, or
(ii) $X$ is regular.

Corollary 1.4. [9, Theorem 3.3] Let $(X, \preceq, d)$ be an ordered complete metric space and $T: X \rightarrow X$ be a nondecreasing map such that $x_{0} \preceq T x_{0}$ for some $x_{0} \in X$ and for every comparable elements $x, y \in X$,

$$
\begin{equation*}
\psi(d(T x, T y)) \leq \psi\left(m_{T}(x, y)\right)-\phi\left(m_{T}(x, y)\right) \tag{1.2}
\end{equation*}
$$

where $(\psi, \varphi)$ is a pair of control functions. Then, in each of the following two cases, $T$ has a fixed point.
(i) $T$ is continuous, or
(ii) $X$ is regular.

Theorem 1.5. [9, Theorem 3.4] Let $(X, \preceq, d)$ be an ordered complete metric space and $(T, S)$ be a weakly increasing par of self-maps on $X$. Suppose that there exist a pair of control functions $(\psi, \varphi)$ such that for any two comparable elements $x, y \in X$,

$$
\psi(d(T x, S y)) \leq \psi(n(x, y))-\phi(n(x, y)) .
$$

Then in each of the following two cases the mappings $T$ and $S$ have at least one common fixed point:
(i) $T$ either $S$ is continuous, or
(ii) $X$ is regular.

Theorem 1.6. [9, Theorem 4.3] Let all the conditions of Corollary 1.4 be fulfilled and let the following condition hold:
(a) for arbitrary two points $x, y \in X$ there exists $z \in X$ which is comparable with both $x$ and $y$.

Then the fixed point of $T$ is unique.
In the first part of this paper, with presenting an example, it is shown that Theorem 1.6 is not true as it stands. Then, it is shown that, by adding a suitable condition, the uniqueness of common fixed point can be proved.

## 2 Main Results

The following example indicates that Theorem 1.6 may fail.
Example 2.1. Let $X=\{O=(0,0), A=(2,2), B=(0,2), C=(2,0)\} \subseteq \mathbb{R}^{2}$ be endowed with the metric $d$ defined by

$$
d\left(\left(x_{1}, x_{2}\right),\left(y_{1}, y_{2}\right)\right)=\sqrt{\left|x_{1}-y_{1}\right|^{2}+\left|x_{2}-y_{2}\right|^{2}}
$$

Suppose that relation $\preceq$ is defined on $X$ as follows:

$$
\preceq=\{(O, O),(A, A),(B, B),(C, C),(B, O),(B, A),(C, O),(C, A)\} .
$$

Then $(X, \preceq, d)$ is a regular ordered complete metric space. Suppose that $T: X \rightarrow X$ is defined as follows:

$$
T(O)=O, T(A)=A, T(B)=C, T(C)=B
$$

Then, $T$ is nondecreasing with respect to $\preceq$ and $O \preceq O=T O$. Choosing $\psi(t)=t$ and $\varphi(t)=\frac{t}{a}$ for any $t \geq 0$, where $a \geq 2+\sqrt{2}$ is a real number, one can verify that, all conditions of Theorem 1.6 are satisfied. Indeed, for the points $A$ and $B$, we have $A \preceq \succeq B$ and

$$
\psi(d(T A, T B))=\psi(d(A, C))=2
$$

On the other hand

$$
\begin{aligned}
m_{T}(A, B) & =\max \left\{d(A, B), d(A, A), d(B, C), \frac{d(A, C)+d(B, A)}{2}\right\} \\
& =\max \{2,0,2 \sqrt{2}, 2\} \\
& =2 \sqrt{2}
\end{aligned}
$$

Thus, one has

$$
\begin{aligned}
\psi\left(m_{T}(A, B)\right)-\varphi\left(m_{T}(A, B)\right) & =\psi(2 \sqrt{2})-\varphi(2 \sqrt{2}) \\
& =2 \sqrt{2}-\frac{2 \sqrt{2}}{a} \\
& \geq 2 \text { (because } a \geq 2+\sqrt{2})
\end{aligned}
$$

Consequently

$$
\psi(d(T A, T B)) \leq \psi\left(m_{T}(A, B)\right)-\varphi\left(m_{T}(A, B)\right)
$$

The case of points $A$ and $C$ is treated similarly since it is really the same as the case of points $A$ and $B$. Again, for the points $O$ and $C$, we have $O \preceq \succeq C$ and

$$
\psi(d(T O, T C))=\psi(d(O, B))=2
$$

On the other hand we have

$$
\begin{aligned}
m_{T}(O, C) & =\max \left\{d(O, C), d(O, O), d(C, B), \frac{d(O, B)+d(C, O)}{2}\right\} \\
& =\max \{2,0,2 \sqrt{2}, 2\} \\
& =2 \sqrt{2}
\end{aligned}
$$

Thus, we get

$$
\begin{aligned}
\psi\left(m_{T}(O, C)\right)-\varphi\left(m_{T}(O, C)\right) & =\psi(2 \sqrt{2})-\varphi(2 \sqrt{2}) \\
& =2 \sqrt{2}-\frac{2 \sqrt{2}}{a} \\
& \geq 2 \text { (because } a \geq 2+\sqrt{2}) .
\end{aligned}
$$

Consequently, we have

$$
\psi(d(T O, T C)) \leq \psi\left(m_{T}(O, C)\right)-\varphi\left(m_{T}(O, C)\right)
$$

The case of points $O$ and $B$ is treated similarly since it is really the same as the case of points $O$ and $C$. So, the relation (1.1) is established for any two comparable elements of $X$. Also, it is clear that the condition (a) is reliable. Thus, all the conditions of Theorem 1.6 be fulfilled. However, $O$ and $A$ are distinct fixed points of $T$.

Note that these two fixed points of $T$ are incomparable; there are two points ( $B$ and $C$ ) which are comparable to both of them, but none of them satisfies the condition $Z \preceq T Z$.

The preceding example shows that the condition (a) in Theorem 1.6 can not grantee the uniqueness of the fixed point and the theorem contains a gap. In the next result, by assuming an additional condition, this result can be repaired.

Theorem 2.2. Let $(X, \preceq, d)$ be an ordered complete metric space and $T: X \rightarrow X$ be a nondecreasing map such that, for every comparable elements $x, y \in X$,

$$
\begin{equation*}
\psi(d(T x, T y)) \leq \psi\left(m_{T}(x, y)\right)-\phi\left(m_{T}(x, y)\right) \tag{2.1}
\end{equation*}
$$

where $(\psi, \varphi)$ is a pair of control functions. Also suppose that the following condition holds:
(b) for arbitrary non-comparable elements $x, y \in X$ there exists $z \in X$ which is comparable with $x$ and $y$ and $z \preceq T z$. Then, in each of the following two cases, $T$ has a unique fixed point.
(i) $T$ is continuous, or
(ii) $X$ is regular.

Proof . We first claim that the fixed points set of $T$ is nonempty. Indeed, if $X$ is a singleton set, say $X=\left\{x_{0}\right\}$, then $x_{0}=T\left(x_{0}\right)$ and $x_{0}$ is the unique fixed point of $T$. So, one can suppose that $X$ has at least two distinct elements. One can consider following two cases:
(I) any two elements of $X$ are comparable. In this case, one of the following two state occurs:
( $\left.I_{1}\right) x_{0} \preceq T\left(x_{0}\right)$, for some $x_{0} \in X$.
In this case, it follows from Corollary 1.4 , that $T$ has a fixed point and the claim is proved.
( $\left.I_{2}\right) T(x) \preceq x$, for any $x \in X$. (Notice that any two elements of $X$ are comparable)
We define a new order $\ll$ on $X$ as follows:

$$
x \ll y \Leftrightarrow y \preceq x,
$$

for any $x, y \in X$. Now, for any $x \in X$, we have $x \ll T x$. It is easy to verify that, all the conditions of Corollary 1.4 are satisfied for $(X, \ll, d)$, except (maybe) the regularity of ( $X, \ll, d$ ) which we do not need it here (Because, any two elements of $X$ are comparable). So by Corollary $1.4, T$ has a fixed point $z$ in $(X, \ll, d)$. It is clear that $z$ is a fixed point of $T$ in $(X, \preceq, d)$.
(II) there exist at least two incomparable points in $X$. With this assumption, our claim is proved by combining the condition (b)and Corollary 1.4

Now let $u$ and $v$ be two fixed points of $T$. One of the following two cases can occurs:
(1) $u \preceq \succeq v$. In this case, we have

$$
\begin{aligned}
\psi(d(u, v)) & =\psi(d(T u, T v) \\
& \leq \psi\left(m_{T}(u, v)\right)-\phi\left(m_{T}(u, v)\right)
\end{aligned}
$$

where

$$
\begin{aligned}
m_{T}(u, v) & =\max \left\{d(u, v), d(u, T u), d(v, T v), \frac{d(u, T v)+d(v, T u)}{2}\right\} \\
& =\max \left\{d(u, v), 0,0, \frac{d(u, v)+d(v, u)}{2}\right\} \\
& =d(u, v)
\end{aligned}
$$

Thus, it follows that

$$
\psi(d(u, v)) \leq \psi(d(u, v))-\phi(d(u, v)),
$$

which is a contradiction unless $d(u, v)=0$, i.e., $u=v$.
(2) $u$ and $v$ are not comparable. In this case by the hypothesis (b), there exists $z \in X$ such that $z \preceq \succeq u$ and $z \preceq \succeq v$ and $z \preceq T z$. Put $y_{n}:=T^{n} y$, for any $y \in X$ and $n \geq 0$. Since $T$ is nondecreasing, we obtain that $u=u_{n} \preceq \succeq z_{n}$, $v=v_{n} \preceq \succeq z_{n}$ for each $n \geq 0$. If there exists $n_{0} \geq 0$ such that, $z_{n_{0}}=u$ then $v \preceq \succeq z_{n_{0}}=u$ and so from item (1), $u=v$. Thus, we can assume that $z_{n} \neq u, \forall n \geq 0$. Since $z \preceq T z$,, proceeding as in the proof of 9, Theorem 3.1], one can conclude that $\left\{z_{n}\right\}$ is a convergent sequence and

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d\left(z_{n-1}, z_{n}\right)=0 \tag{2.2}
\end{equation*}
$$

Now, we claim that

$$
\lim _{n \rightarrow \infty} d\left(u, z_{n}\right)=0
$$

Indeed, for any $n \geq 1$ we have

$$
u=u_{n} \preceq \succeq z_{n} .
$$

Hence,

$$
\begin{aligned}
\psi\left(d\left(u, z_{n}\right)\right) & =\psi\left(d\left(T u_{n-1}, T z_{n-1}\right)\right. \\
& \leq \psi\left(m_{T}\left(u_{n-1}, z_{n-1}\right)\right)-\phi\left(m_{T}\left(u_{n-1}, z_{n-1}\right)\right) \\
& \leq \psi\left(m_{T}\left(u, z_{n-1}\right)\right)-\phi\left(m_{T}\left(u, z_{n-1}\right)\right) \\
& <\psi\left(m_{T}\left(u, z_{n-1}\right)\right)\left(\text { becausem }_{T}\left(u, z_{n-1}\right) \neq 0\right)
\end{aligned}
$$

where

$$
\begin{aligned}
m_{T}\left(u, z_{n-1}\right) & =\max \left\{d\left(u, z_{n-1}\right), d(u, T u), d\left(z_{n-1}, T z_{n-1}\right), \frac{d\left(u, T z_{n-1}\right)+d\left(z_{n-1}, T u\right)}{2}\right\} \\
& =\max \left\{d\left(u, z_{n-1}\right), d\left(z_{n-1}, z_{n}\right), \frac{d\left(u, z_{n}\right)+d\left(z_{n-1}, u\right)}{2}\right\}
\end{aligned}
$$

Using the fact that $\psi$ is a nondecreasing function, it follows that

$$
\begin{equation*}
d\left(u, z_{n}\right)<\max \left\{d\left(u, z_{n-1}\right), d\left(z_{n-1}, z_{n}\right), \frac{d\left(u, z_{n}\right)+d\left(z_{n-1}, u\right)}{2}\right\} \tag{2.3}
\end{equation*}
$$

Now, one can consider the following two cases:
$\left(i_{1}\right)$ there exists a sequence $\left\{n_{k}\right\}_{k \geq 0}$ of distinct positive integers that

$$
d\left(u, z_{n_{k}-1}\right) \leq d\left(z_{n_{k}-1}, z_{n_{k}}\right)
$$

In this case, 2.2 implies that

$$
\lim _{k \rightarrow \infty} d\left(u, z_{n_{k}-1}\right)=0
$$

and using the fact that $\left\{z_{n}\right\}$ is a convergent sequence, one can conclude that

$$
\lim _{n \rightarrow \infty} d\left(u, z_{n}\right)=0
$$

( $i_{2}$ ) there exists $n_{0} \geq 1$ such that

$$
d\left(u, z_{n}\right)>d\left(z_{n-1}, z_{n}\right)
$$

for any $n \geq n_{0}$. In this case, 2.2 implies that, for any $n \geq n_{0}$

$$
\begin{aligned}
d\left(u, z_{n}\right) & <\max \left\{d\left(u, z_{n-1}\right), d\left(u, z_{n}\right), \frac{d\left(u, z_{n}\right)+d\left(z_{n-1}, u\right)}{2}\right\} \\
& =\max \left\{d\left(u, z_{n-1}\right), d\left(u, z_{n}\right)\right\} .
\end{aligned}
$$

So, one can conclude that

$$
d\left(u, z_{n}\right)<d\left(u, z_{n-1}\right)
$$

for any $n \geq n_{0}$. Thus, for any, the sequence $\left\{d\left(u, z_{n}\right)\right\}_{n \geq n_{0}}$ is non-increasing and bounded below. So, it has a limit $l \geq 0$. In addition, we have:

$$
\lim _{n \rightarrow \infty} m_{T}\left(u, z_{n-1}\right)=l .
$$

Passing to (upper)limit in the relation

$$
\psi\left(d\left(u, z_{n}\right)\right) \leq \psi\left(m_{T}\left(u, z_{n-1}\right)\right)-\phi\left(m_{T}\left(u, z_{n-1}\right)\right)
$$

one concludes that

$$
\psi(l)) \leq \psi(l)-\phi(l)
$$

Which is a contradiction unless $l=0$. So, in any case, we proved that

$$
\lim _{n \rightarrow \infty} d\left(u, z_{n}\right)=0 .
$$

In the same way, one can show that

$$
\lim _{n \rightarrow \infty} d\left(v, z_{n}\right)=0
$$

Finally, for any $n \geq 0$, we have

$$
0 \leq d(u, v) \leq d\left(u, z_{n}\right)+d\left(v, z_{n}\right)
$$

Letting $n \rightarrow \infty$, we obtain that $d(u, v)=0$, i.e., $u=v$.
Hence, in any case, the fixed point of $T$ is unique.
Theorem 2.3. Assume that all the conditions of Corollary 1.4 are satisfied. Also suppose that the following condition holds:
(c) for arbitrary non-comparable two fixed points $x, y \in X$ there exists $z \in X$ which is comparable with $x$ and $y$, and also $z \preceq T z$.

Then $T$ has a unique fixed point.
Proof . By Corollary $1.4, T$ has at least a fixed point. Remainder of proof is similar to Theorem 2.2,
Theorem 2.4. Assume that all the conditions of Corollary 1.4 are satisfied. Then $T$ has a unique fixed point if and only if the set of all fixed points of $T$ is well ordered.

Proof . By Corollary 1.4, $T$ has at least a fixed point. Now, if the fixed point of $T$ is unique then the set of all fixed points of $T$ is a singleton and so is well ordered.

Conversely, suppose that the set of all fixed points of $T$ is well ordered, and $u$ and $v$ are two distinct fixed point of $T$. Then $u \preceq \succeq v$. Similarly as in the proof of item (1) in Theorem 2.2 it can be shown that $u=v$.

Remark 2.5. If $m_{T}(x, y)$ is replaced by $n_{T}(x, y)$ in the Theorem 2.3 then we can replace the condition (b) by the condition (a), i.e., we have the following theorem:

Theorem 2.6. Let $(X, \preceq, d)$ be an ordered complete metric space and $T: X \rightarrow X$ be a nondecreasing map such that $x_{0} \preceq T x_{0}$, for some $x_{0} \in X$ and for any two comparable elements $x, y \in X$,

$$
\begin{equation*}
\psi(d(T x, T y)) \leq \psi\left(n_{T}(x, y)\right)-\phi\left(n_{T}(x, y)\right) \tag{2.4}
\end{equation*}
$$

where $(\psi, \varphi)$ is a pair of control functions. Furthermore, let the condition (a) of Theorem 1.6 hold. If $T$ is continuous or $X$ is regular, then $T$ has a unique fixed point.

Proof . Firstly, similar to the proof of Corollary 1.4. One can conclude that $T$ has a fixed point.
Now, let $u$ and $v$ be two fixed points of $T$. One can consider the following two cases:
(1) $u \preceq \succeq v$.

In this case, similarly as in the proof of item (1) in Theorem 2.2, it can be shown that $u=v$.
(2) $u$ and $v$ are not comparable.

In this case by the hypothesis (a) of Theorem 1.6, there exist $z \in X$ such that $z \preceq \succeq u$ and $z \preceq \succeq v$.
By using the employed notations in the proof of Theorem 2.2 . (without lose of generality) one can suppose that $z_{n} \neq u$, for all $n \geq 0$ and prove that $u=u_{n} \preceq \succeq z_{n}$ and $v=v_{n} \preceq \succeq z_{n}$ for each $n \geq 0$. Now, for any $n \geq 1$, $u=u_{n} \preceq \succeq z_{n}$, hence,

$$
\begin{aligned}
\psi\left(d\left(u, z_{n}\right)\right) & =\psi\left(d\left(T u_{n-1}, T z_{n-1}\right)\right. \\
& \leq \psi\left(n_{T}\left(u_{n-1}, z_{n-1}\right)\right)-\phi\left(n_{T}\left(u_{n-1}, z_{n-1}\right)\right) \\
& \leq \psi\left(n_{T}\left(u, z_{n-1}\right)\right)-\phi\left(n_{T}\left(u, z_{n-1}\right)\right)
\end{aligned}
$$

where

$$
\begin{aligned}
n_{T}\left(u, z_{n-1}\right) & =\max \left\{d\left(u, z_{n-1}\right), \frac{d(u, T u)+d\left(z_{n-1}, T z_{n-1}\right)}{2}, \frac{d\left(u, T z_{n-1}\right)+d\left(z_{n-1}, T u\right)}{2}\right\} \\
& =\max \left\{d\left(u, z_{n-1}\right), \frac{d\left(z_{n-1}, z_{n}\right)}{2}, \frac{d\left(u, z_{n}\right)+d\left(z_{n-1}, u\right)}{2}\right\} \\
& \leq \max \left\{d\left(u, z_{n-1}\right), \frac{d\left(z_{n-1}, u\right)+d\left(u, z_{n}\right)}{2}, \frac{d\left(u, z_{n}\right)+d\left(z_{n-1}, u\right)}{2}\right\} \\
& =\max \left\{d\left(u, z_{n-1}\right), \frac{d\left(z_{n-1}, u\right)+d\left(u, z_{n}\right)}{2}\right\} \\
& \leq \max \left\{d\left(u, z_{n-1}\right), d\left(u, z_{n}\right)\right\} .
\end{aligned}
$$

Similar to the proof of Theorem 2.2 one can complete the proof.
Example 2.7. As we saw, in the Example 2.4, the condition (a) is hold, but the mapping $T$ has two distinct fixed points. Now, notice that, the condition (b) of the Theorem 2.2 is not satisfied. In fact, for the points $A$ and $O$ there is no $Z \in X$ which is comparable with $A$ and $O$ and $Z \preceq T Z$. Also, notice that, the mapping $T$ is not satisfied in the Theorem 2.6. Indeed,, for the points $A$ and $B$ we have $A \preceq \succeq B$ and

$$
\begin{aligned}
n_{T}(A, B) & =\max \left\{d(A, B), \frac{d(A, A)+d(B, C)}{2}, \frac{d(A, C)+d(B, A)}{2}\right\} \\
& =\max \{2, \sqrt{2}, 2\} \\
& =2
\end{aligned}
$$

So, for any pair $(\psi, \varphi)$ of control functions we have:

$$
\psi(d(T A, T B))=\psi(d(A, C))=\psi(2)
$$

Also,

$$
\begin{aligned}
\psi\left(n_{T}(A, B)\right)-\varphi\left(n_{T}(A, B)\right) & =\psi(2)-\varphi(2) \\
& <\psi(2)(\text { because } \varphi(2)>0) \\
& =\psi(d(T A, T B)) .
\end{aligned}
$$

Hence the conditions (2.4) of Theorem 2.4 is not satisfy. Finally, note that all conditions of Theorem 2.3 are satisfied, except condition (c) which is not established. In fact, $O$ and $A$ are two non comparable fixed points of $T$ and there is no $Z \in X$ which is comparable with $O, A$ and $T Z$.

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