



A Unique Common Fixed Point Theorem for Six Maps in G -metric Spaces

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Abstract

In this paper we obtain a unique common fixed point theorem for six weakly compatible mappings in G -metric spaces.

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1. Introduction

Dhage [1, 2, 3, 4] et al. introduced the concept of D -metric spaces as generalization of ordinary metric functions and went on to present several fixed point results for single and multivalued mappings. Mustafa and Sims [12] and Naidu et al. [8, 9, 10] demonstrated that most of the claims concerning the fundamental topological structure of D -metric space are incorrect, alternatively, Mustafa and Sims introduced in [13] more appropriate notion of generalized metric space which called G -metric spaces, and obtained some topological properties. Later Zead Mustafa, Hamed Obiedat and Fadi Awawdeh [13], Mustafa, Shatanawi and Bataineh [15], Mustafa and Sims [16], Shatanawi [11] and Renu Chugh, Tamanna Kadian, Anju Rani and B.E. Rhoades [7] et al. obtained some fixed point theorems for a single map in G -metric spaces. In this paper, we obtain a unique common fixed point theorem for six weakly compatible mappings in G -metric spaces and obtain some theorems of [11] as corollaries to our theorem. First, we present some known definitions and propositions in G -metric spaces.

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Definition 1.1. [13]. Let X be a nonempty set and let $G : X \times X \times X \rightarrow R^+$ be a function satisfying the following properties :

(G_1): $G(x, y, z) = 0$ if $x = y = z$,

(G_2): $0 < G(x, x, y)$ for all $x, y \in X$ with $x \neq y$,

(G_3): $G(x, x, y) \leq G(x, y, z)$ for all $x, y, z \in X$ with $y \neq z$,

(G_4): $G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$, symmetry in all three variables,

(G_5): $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$ for all $x, y, z, a \in X$.

Then the function G is called a generalized metric or a G -metric on X and the pair (X, G) is called a G -metric space.

Definition 1.2. [13]. Let (X, G) be a G -metric space and $\{x_n\}$ be a sequence in X . A point $x \in X$ is said to be limit of $\{x_n\}$ iff $\lim_{n, m \rightarrow \infty} G(x, x_n, x_m) = 0$. In this case, the sequence $\{x_n\}$ is said to be G -convergent to x .

Definition 1.3. [13]. Let (X, G) be a G -metric space and $\{x_n\}$ be a sequence in X . $\{x_n\}$ is called G -Cauchy iff $\lim_{n, m, l \rightarrow \infty} G(x_l, x_n, x_m) = 0$. (X, G) is called G -complete if every G -Cauchy sequence in (X, G) is G -convergent in (X, G) .

Proposition 1.4. [13] In a G -metric space, (X, G) , the following are equivalent.

(1) The sequence $\{x_n\}$ is G -Cauchy.

(2) For every $\epsilon > 0$, there exists $N \in \mathbf{N}$ such that $G(x_n, x_m, x_m) < \epsilon$, for all $n, m \geq N$.

Proposition 1.5. [13]. Let (X, G) be a G -metric space. Then the function $G(x, y, z)$ is jointly continuous in all three of its variables.

Proposition 1.6. [13]. Let (X, G) be a G -metric space. Then for any $x, y, z, a \in X$, it follows that

(i) if $G(x, y, z) = 0$ then $x = y = z$,

(ii) $G(x, y, z) \leq G(x, x, y) + G(x, x, z)$,

(iii) $G(x, y, y) \leq 2G(x, x, y)$,

(iv) $G(x, y, z) \leq G(x, a, z) + G(a, y, z)$,

(v) $G(x, y, z) \leq \frac{2}{3}[G(x, a, a) + G(y, a, a) + G(z, a, a)]$.

Proposition 1.7. [13]. Let (X, G) be a G -metric space. Then for a sequence $\{x_n\} \subseteq X$ and a point $x \in X$, the following are equivalent

(i) $\{x_n\}$ is G -convergent to x ,

(ii) $G(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow \infty$,

(iii) $G(x_n, x, x) \rightarrow 0$ as $n \rightarrow \infty$,

(iv) $G(x_m, x_n, x) \rightarrow 0$ as $m, n \rightarrow \infty$.

Definition 1.8. [13] Let (X, G) and (X', G') be two G -metric spaces, and let $f : (X, G) \rightarrow (X', G')$ be a function, then f is said to be G -continuous at a point $a \in X$ if and only if, given $\epsilon > 0$, there exists $\delta > 0$ such that $x, y \in X$; and $G(a, x, y) < \delta$ implies $G'(f(a), f(x), f(y)) < \epsilon$. A function f is G -continuous at X if and only if it is G -continuous at all $a \in X$.

Proposition 1.9. [13] Let (X, G) , and (X', G') be two G -metric spaces. Then a function $f : X \rightarrow X'$ is G -continuous at a point $x \in X$ if and only if it is G -sequentially continuous at x ; that is, whenever (x_n) is G -convergent to x we have $(f(x_n))$ is G -convergent to $f(x)$.

Definition 1.10. [5] A pair of self mappings is called weakly compatible if they commute at their coincidence points.

2. Main Results

Following to Matkowski [6], let Φ denote the set of all continuous nondecreasing functions $\phi : [0, \infty) \rightarrow [0, \infty)$ such that $\phi^n(t) \rightarrow 0$ as $n \rightarrow \infty$ for all $t > 0$. It is clear that $\phi(t) < t$ for all $t > 0$ and $\phi(0) = 0$.

Theorem 2.1. *Let (X, G) be a G -metric space and $S, T, R, f, g, h : X \rightarrow X$ be satisfying*

- (i) $S(X) \subseteq g(X), T(X) \subseteq h(X)$ and $R(X) \subseteq f(X)$,
- (ii) one of $f(X), g(X)$ and $h(X)$ is a complete subspace of X ,
- (iii) the pairs $(S, f), (T, g)$ and (R, h) are weakly compatible, and

$$(iv) \ G(Sx, Ty, Rz) \leq \phi \left(\max \left\{ \begin{array}{l} G(fx, gy, hz), \\ \frac{1}{3}[G(fx, Sx, Ty) + G(gy, Ty, Rz) + G(hz, Rz, Sx)], \\ \frac{1}{4}[G(fx, Ty, hz) + G(Sx, gy, hz) + G(fx, gy, Rz)] \end{array} \right\} \right)$$

for all $x, y, z \in X$, where $\phi \in \Phi$.

Then either one of the pairs $(S, f), (T, g)$ and (R, h) has a coincidence point or the maps S, T, R, f, g and h have a unique common fixed point in X .

Proof . Choose $x_0 \in X$. By (i), there exist $x_1, x_2, x_3 \in X$ such that $Sx_0 = gx_1 = y_0$, say , $Tx_1 = hx_2 = y_1$, say and $Rx_2 = fx_3 = y_2$, say.

Inductively, there exist sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$y_{3n} = Sx_{3n} = gx_{3n+1}, y_{3n+1} = Tx_{3n+1} = hx_{3n+2}, \text{ and } y_{3n+2} = Rx_{3n+2} = fx_{3n+3}, \text{ where } n = 0, 1, 2, \dots$$

If $y_{3n} = y_{3n+1}$ then x_{3n+1} is a coincidence point of g and T .

If $y_{3n+1} = y_{3n+2}$ then x_{3n+2} is a coincidence point of h and R .

If $y_{3n+2} = y_{3n+3}$ then x_{3n+3} is a coincidence point of f and S .

Now assume that $y_n \neq y_{n+1}$ for all n .

Denote $d_n = G(y_n, y_{n+1}, y_{n+2})$.

Putting $x = x_{3n}, y = x_{3n+1}, z = x_{3n+2}$ in (iv), we get

$$\begin{aligned} d_{3n} &= G(y_{3n}, y_{3n+1}, y_{3n+2}) = \\ &G(Sx_{3n}, Tx_{3n+1}, Rx_{3n+2}) \\ &\leq \phi \left(\max \left\{ \begin{array}{l} G(fx_{3n}, gx_{3n+1}, hx_{3n+2}), \frac{1}{3}[G(fx_{3n}, Sx_{3n}, Tx_{3n+1}) + \\ G(gx_{3n+1}, Tx_{3n+1}, Rx_{3n+2}) + G(hx_{3n+2}, Rx_{3n+2}, Sx_{3n})], \\ \frac{1}{4}[G(fx_{3n}, Tx_{3n+1}, hx_{3n+2}) + G(Sx_{3n}, gx_{3n+1}, hx_{3n+2}) \\ + G(fx_{3n}, gx_{3n+1}, Rx_{3n+2})] \end{array} \right\} \right) \\ &= \phi \left(\max \left\{ \begin{array}{l} G(y_{3n-1}, y_{3n}, y_{3n+1}), \frac{1}{3}[G(y_{3n-1}, y_{3n}, y_{3n+1}) + \\ G(y_{3n}, y_{3n+1}, y_{3n+2}) + G(y_{3n+1}, y_{3n+2}, y_{3n})], \\ \frac{1}{4}[G(y_{3n-1}, y_{3n+1}, y_{3n+1}) + G(y_{3n}, y_{3n}, y_{3n+1}) \\ + G(y_{3n-1}, y_{3n}, y_{3n+2})] \end{array} \right\} \right) \\ &\leq \phi \left(\max \left\{ \begin{array}{l} d_{3n-1}, \frac{1}{3}[d_{3n-1} + d_{3n} + d_{3n}], \\ \frac{1}{4}[d_{3n-1} + d_{3n} + (d_{3n-1} + d_{3n})] \end{array} \right\} \right) \end{aligned} \tag{1}$$

If $d_{3n} \geq d_{3n-1}$ then from (1), we have $d_{3n} \leq \phi(d_{3n}) < d_{3n}$. It is a contradiction. Hence $d_{3n} \leq d_{3n-1}$.

Now from (1), $d_{3n} \leq \phi(d_{3n-1})$.

Similarly, by putting $x = x_{3n+3}, y = x_{3n+1}, z = x_{3n+2}$ and $x = x_{3n+3},$

$y = x_{3n+4}, z = x_{3n+2}$ in (iv), we get

$$d_{3n+1} \leq \phi(d_{3n}) \tag{2}$$

and

$$d_{3n+2} \leq \phi(d_{3n+1}) \tag{3}$$

respectively. Thus from (1),(2) and (3), we have

$$\begin{aligned} G(y_n, y_{n+1}, y_{n+2}) &\leq \phi(G(y_{n-1}, y_n, y_{n+1})) \\ &\leq \phi^2(G(y_{n-2}, y_{n-1}, y_n)) \\ &\vdots \\ &\leq \phi^n(G(y_0, y_1, y_2)) \end{aligned} \tag{4}$$

From (G_3) and (4), we have

$$G(y_n, y_n, y_{n+1}) \leq G(y_n, y_{n+1}, y_{n+2}) \leq \phi^n(G(y_0, y_1, y_2)).$$

Now for $m > n$, from (G_5) and (4), we have

$$\begin{aligned} G(y_n, y_n, y_m) &\leq G(y_n, y_n, y_{n+1}) + G(y_{n+1}, y_{n+1}, y_{n+2}) + \dots + G(y_{m-1}, y_{m-1}, y_m) \\ &\leq \phi^n(G(y_0, y_1, y_2)) + \phi^{n+1}(G(y_0, y_1, y_2)) + \dots + \phi^{m-1}(G(y_0, y_1, y_2)) \\ &\rightarrow 0 \text{ as } n \rightarrow \infty, \text{ since } \phi^n(t) \rightarrow 0 \text{ as } n \rightarrow \infty \text{ for all } t > 0. \end{aligned}$$

Hence $\{y_n\}$ is G -Cauchy. Suppose $f(X)$ is G -complete.

Then there exist $p, t \in X$ such that $y_{3n+2} \rightarrow p = ft$. Since $\{y_n\}$ is G -Cauchy, it follows that $y_{3n} \rightarrow p$ and $y_{3n+1} \rightarrow p$ as $n \rightarrow \infty$.

$$\begin{aligned} &G(St, Tx_{3n+1}, Rx_{3n+2}) \\ &\leq \phi \left(\max \left\{ \begin{array}{l} G(ft, gx_{3n+1}, hx_{3n+2}), \frac{1}{3}[G(ft, St, Tx_{3n+1}) + \\ G(gx_{3n+1}, Tx_{3n+1}, Rx_{3n+2}) + G(hx_{3n+2}, Rx_{3n+2}, St)], \\ \frac{1}{4}[G(ft, Tx_{3n+1}, hx_{3n+2}) + G(St, gx_{3n+1}, hx_{3n+2}) \\ + G(ft, gx_{3n+1}, Rx_{3n+2})] \end{array} \right\} \right) \end{aligned}$$

Letting $n \rightarrow \infty$, we get

$$G(St, p, p) \leq \phi \left(\max \left\{ \begin{array}{l} 0, \frac{1}{3}[G(p, St, p) + 0 + G(p, p, St)], \\ \frac{1}{4}[0 + G(St, p, p) + 0] \end{array} \right\} \right).$$

$$G(St, p, p) \leq \phi(G(St, p, p)), \text{ since } \phi \text{ is nondecreasing.}$$

Hence $St = p$. Thus $p = ft = St$.

Since the pair (S, f) is weakly compatible, we have $fp = Sp$.

Putting $x = p, y = x_{3n+1}, z = x_{3n+2}$ in (iv), we get

$$\begin{aligned} &G(Sp, Tx_{3n+1}, Rx_{3n+2}) \\ &\leq \phi \left(\max \left\{ \begin{array}{l} G(fp, gx_{3n+1}, hx_{3n+2}), \frac{1}{3}[G(fp, Sp, Tx_{3n+1}) + \\ G(gx_{3n+1}, Tx_{3n+1}, Rx_{3n+2}) + G(hx_{3n+2}, Rx_{3n+2}, Sp)], \\ \frac{1}{4}[G(fp, Tx_{3n+1}, hx_{3n+2}) + G(Sp, gx_{3n+1}, hx_{3n+2}) \\ + G(fp, gx_{3n+1}, Rx_{3n+2})] \end{array} \right\} \right) \end{aligned}$$

Letting $n \rightarrow \infty$, we have

$$G(Sp, p, p) \leq \phi \left(\max \left\{ \begin{array}{l} G(Sp, p, p), \frac{1}{3}[G(Sp, Sp, p) + 0 + G(p, p, Sp)], \\ \frac{1}{4}[G(Sp, p, p) + G(Sp, p, p) + G(Sp, p, p)] \end{array} \right\} \right)$$

$$\text{Since } G(Sp, Sp, p) \leq 2G(Sp, p, p), \text{ we have } G(Sp, p, p) \leq \phi(G(Sp, p, p))$$

Thus $Sp = p$. Hence $fp = Sp = p$.

(5)

Since $p = Sp \in g(X)$, there exists $v \in X$ such that $p = gv$.
 Putting $x = p, y = v, z = x_{3n+2}$ in (iv), we get

$$G(Sp, Tv, Rx_{3n+2}) \leq \phi \left(\max \left\{ \begin{array}{l} G(fp, gv, hx_{3n+2}), \frac{1}{3}[G(fp, Sp, Tv) + \\ G(gv, Tv, Rx_{3n+2}) + G(hx_{3n+2}, Rx_{3n+2}, Sp)], \\ \frac{1}{4}[G(fp, Tv, hx_{3n+2}) + G(Sp, gv, hx_{3n+2}) \\ + G(fp, gv, Rx_{3n+2})] \end{array} \right\} \right)$$

Letting $n \rightarrow \infty$, we deduce that

$$G(p, Tv, p) \leq \phi \left(\max \left\{ \begin{array}{l} 0, \frac{1}{3}[G(p, p, Tv) + G(p, Tv, p) + 0], \\ \frac{1}{4}[G(p, Tv, p) + 0 + 0] \end{array} \right\} \right) \\ \leq \phi(G(p, Tv, p)) \text{ , since } \phi \text{ is nondecreasing.}$$

Thus $Tv = p$, so that $p = Tv = gv$.

Since the pair (T, g) is weakly compatible, we have $Tp = gp$.

$$G(Sp, Tp, Rx_{3n+2}) \leq \phi \left(\max \left\{ \begin{array}{l} G(fp, gp, hx_{3n+2}), \frac{1}{3}[G(fp, Sp, Tp) + \\ G(gp, Tp, Rx_{3n+2}) + G(hx_{3n+2}, Rx_{3n+2}, Sp)], \\ \frac{1}{4}[G(fp, Tp, hx_{3n+2}) + G(Sp, gp, hx_{3n+2}) \\ + G(fp, gp, Rx_{3n+2})] \end{array} \right\} \right)$$

Letting $n \rightarrow \infty$, we have

$$G(p, Tp, p) \leq \phi \left(\max \left\{ \begin{array}{l} G(p, Tp, p), \frac{1}{3}[G(p, p, Tp) + G(Tp, Tp, p) + 0], \\ \frac{1}{4}[G(p, Tp, p) + G(p, Tp, p) + G(p, Tp, p)] \end{array} \right\} \right),$$

Since $G(Tp, Tp, p) \leq 2G(Tp, p, p)$, we have, $G(p, Tp, p) \leq \phi(G(p, Tp, p))$.

Thus $Tp = p$. Hence $gp = Tp = p$. (6)

Since $p = Tp \in h(X)$, there exists $w \in X$ such that $p = hw$.

Putting $x = p, y = p, z = w$ in (iv), we get

$$G(Sp, Tp, Rw) \leq \phi \left(\max \left\{ \begin{array}{l} G(fp, gp, hw), \frac{1}{3}[G(fp, Sp, Tp) + \\ G(gp, Tp, Rw) + G(hw, Rw, Sp)], \\ \frac{1}{4}[G(fp, Tp, hw) + G(Sp, gp, hw) \\ + G(fp, gp, Rw)] \end{array} \right\} \right)$$

$$G(p, p, Rw) \leq \phi \left(\max \left\{ \begin{array}{l} 0, \frac{1}{3}[0 + G(p, p, Rw) + G(p, Rw, p)], \\ \frac{1}{4}[0 + 0 + G(p, p, Rw)] \end{array} \right\} \right)$$

$\leq \phi(G(p, p, Rw))$, since ϕ is nondecreasing.

Thus $Rw = p$, so that $p = hw = Rw$.

Since the pair (R, h) is weakly compatible, we have $Rp = hp$.

Putting $x = p, y = p, z = p$ in (iv), we get

$$G(p, p, Rp) = G(Sp, Tp, Rp) \\ \leq \phi \left(\max \left\{ \begin{array}{l} G(fp, gp, Rp), \frac{1}{3}[0 + \\ G(p, p, Rp) + G(Rp, Rp, p)], \\ \frac{1}{4}[G(p, p, Rp) + G(p, p, Rp) \\ + G(p, p, Rp)] \end{array} \right\} \right)$$

Since $G(Rp, Rp, p) \leq 2G(p, p, Rp)$, we have $G(p, p, Rp) \leq \phi(G(p, p, Rp))$.

Thus $Rp = p$ so that $Rp = hp = p$.

(7)

From (5),(6) and (7), it follows that p is a common fixed point of S, T, R, f, g and h .

Uniqueness of common fixed point follows easily from (iv). Similarly, we can prove the theorem when $g(X)$ or $h(X)$ is a complete subspace of X \square

Corollary 2.2. *Let (X, G) be a G -metric space and $S, T, R, f, g, h : X \rightarrow X$ be satisfying*

(i) $S(X) \subseteq g(X), T(X) \subseteq h(X)$ and $R(X) \subseteq f(X)$,

(ii) one of $f(X), g(X)$ and $h(X)$ is a complete subspace of X ,

(iii) the pairs $(S, f), (T, g)$ and (R, h) are weakly compatible and

(iv) $G(Sx, Ty, Rz) \leq \phi(G(fx, gy, hz))$

for all $x, y, z \in X$, where $\phi \in \Phi$.

Then the maps S, T, R, f, g and h have a unique common fixed point in X .

Corollary 2.3. *Let (X, G) be a complete G -metric space and $S, T, R : X \rightarrow X$ be satisfying*

$G(Sx, Ty, Rz) \leq \phi(G(x, y, z))$ for all $x, y, z \in X$, where $\phi \in \Phi$.

Then the maps S, T and R have a unique common fixed point, say, $p \in X$ and S, T and R are G -continuous at p .

Proof . There exists $p \in X$ such that p is the unique common fixed point of S, T and R as in Theorem 2.1.

Let $\{y_n\}$ be any sequence in X which G -converges to p .

Then

$G(Sy_n, Sp, Sp) = G(Sy_n, Tp, Rp) \leq \phi(G(y_n, p, p)) \rightarrow 0$ as $n \rightarrow \infty$.

Hence S is G -continuous at p .

Similarly, we can show that T and R are also G -continuous at p . \square

Remark 2.4. *Theorem 3.1, Corollaries 3.2 to 3.5 of [11] follows from Corollary 2.3 with $S = T = R$.*

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